
Planck intermediate results

Published in: Astronomy and Astrophysics

DOI: 10.1051/0004-6361/201731489

Published: 01/09/2018

Document Version
Publisher's PDF, also known as Version of record

Please cite the original version:

This material is protected by copyright and other intellectual property rights, and duplication or sale of all or part of any of the repository collections is not permitted, except that material may be duplicated by you for your research use or educational purposes in electronic or print form. You must obtain permission for any other use. Electronic or print copies may not be offered, whether for sale or otherwise to anyone who is not an authorised user.
Planck intermediate results

LIII. Detection of velocity dispersion from the kinetic Sunyaev-Zeldovich effect


(Affiliations can be found after the references)

Received 2 July 2017 / Accepted 12 June 2018

ABSTRACT

Using the Planck full-mission data, we present a detection of the temperature (and therefore velocity) dispersion due to the kinetic Sunyaev-Zeldovich (kSZ) effect from clusters of galaxies. To suppress the primary CMB and instrumental noise we derive a matched filter and then convolve it with the Planck foreground-cleaned “2D–ILC” maps. By using the Meta Catalogue of X-ray detected Clusters of galaxies (MCXC), we determine the normalized rms dispersion of the temperature fluctuations at the positions of clusters, finding that this shows excess variance compared with the noise expectation. We then build an unbiased statistical estimator of the signal, determining that the normalized mean temperature dispersion of 1526 clusters is \( \langle \Delta T / T \rangle \) = (1.64 ± 0.48) × 10^{-11}. However, comparison with analytic calculations and simulations suggest that around 0.7 of this result is due to cluster lensing rather than the kSZ effect. By correcting this, the temperature dispersion is measured to be \( \langle \Delta T / T \rangle \) = (1.35 ± 0.48) × 10^{-11}, which gives a detection at the 2.8σ level. We further convert uniform-weight temperature dispersion into a measurement of the line-of-sight velocity dispersion by using estimates of the optical depth of each cluster (which introduces additional uncertainty into the estimate). We find that the velocity dispersion is \( \langle \sigma_v \rangle = (123 \pm 71)^{\text{km s}^{-1}} \), which is consistent with findings from other large-scale structure studies, and provides direct evidence of statistical homogeneity on scales of 600 h^{-1} Mpc. Our study shows the promise of using cross-correlations of the kSZ effect with large-scale structure in order to constrain the growth of structure.

Key words. cosmic background radiation – large-scale structure of Universe – galaxies: clusters: general – methods: data analysis

1. Introduction

The kinetic Sunyaev-Zeldovich (hereafter kSZ; Sunyaev & Zeldovich 1972, 1980) effect describes the temperature anisotropy of the cosmic microwave background (CMB) radiation due to inverse Compton scattering of CMB photons off a moving cloud of electrons. The effect can be written as

\[ \frac{\Delta T}{T} = -\frac{c}{\sigma_T} \int n_e (\mathbf{v} \cdot \mathbf{r}) d\mathbf{r}, \]

where \( \sigma_T \) is the Thomson cross-section, \( n_e \) is the electron density, \( \mathbf{v} \) is the velocity along the line-of-sight, and \( d\mathbf{r} \) is the path length in the radial direction. By adopting a so-called “pairwise momentum estimator,” i.e., using the weights that quantify the difference in temperature between pairs of galaxies, the effect was first detected by Hand et al. (2012) using CMB maps from the Atacama Cosmology Telescope (ACT). The detection of the kSZ effect has been further solidified using the same pairwise momentum estimator with other CMB data, including Wilkinson Microwave Anisotropy Probe (WMAP) 9-year W-band data, and Planck’s four foreground-cleaned maps (Planck Collaboration Int. XXXVII 2016), and again more recently using a Fourier space analysis (Sugiyama et al. 2018). These measurements represent detections at the 2–3σ level. In addition, De Bernardis et al. (2017) applied the pairwise momentum estimator to the ACT data and 50 000 bright galaxies from BOSS DR11 catalogue, and obtained 3.6–4.1σ C.L. detection. By using the same estimator to the South Pole Telescope (SPT) data and Dark Energy Survey (DES) data, Soergel et al. (2016) achieved the detection of kSZ signal 4.2σ C.L. More recently Li et al. (2018) detected the pairwise kSZ signal for BOSS DR13 low mass group (\( M_h \approx 10^{12} h^{-1} M_\odot \)) by using the 2D–ILC map (see Sect. 2.1.2). Besides the pairwise momentum

* Corresponding author: Y.-Z. Ma, ma@ukzn.ac.za
estimator, in Planck Collaboration Int. XXXVII (2016) the kSZ field and cross-correlated with the reconstructed linear velocity field data \((\delta v \cdot \hat{\mathbf{r}})\) from the Sloan Digital Sky Survey (SDSS-DR7) to compute the correlation function \(\langle \Delta T(\mathbf{r}) \cdot \hat{\mathbf{r}} \rangle\). For this cross-correlation, 3.0–3.2 \(\sigma\) detections were found for the foreground-cleaned Planck maps, and 3.8 \(\sigma\) for the Planck 217-GHz map. Following Planck Collaboration Int. XXXVII (2016), Schaan et al. (2016) detected the aggregated signal of the kSZ effect at 3.3 \(\sigma\) C.L. by cross-correlating the velocity field from BOSS samples with the kSZ map produced from ACT observations. More recently, Hill et al. (2016) cross-correlated the squared kSZ fields from WMAP and Planck, and the projected galaxy overdensity from the Wide-field Infrared Survey Explorer (WISE), which led to a 3 \(\sigma\) detection. With advanced ACTPol and a future Stage-IV CMB experiment, the signal-to-noise ratio (S/N) of the kSZ squared field and projected density field could reach 120 and 150, respectively (Ferraro et al. 2016), although these authors also cautioned that the results should be corrected for a bias due to lensing. These previous attempts to make various kinds of kSZ measurement are summarized in Table 1.

There has been a lot of previous work investigating how to use kSZ measurements to determine the peculiar velocity field. This idea was first proposed by Haehnelt & Tegmark (1996), suggesting that on small angular scales the peculiar velocities of clusters could be inferred from CMB observations. Aghanim et al. (2001) estimated the potential uncertainty of the kSZ measurements due to contamination by the primary CMB and thermal Sunyaev-Zeldovich (hereafter tSZ) effect. In Holzapfel et al. (1997), the peculiar velocities of two distant galaxy clusters, namely Abell 2163 \((z = 0.201)\) and Abell 1689 \((z = 0.181)\), were estimated through millimetre-wavelength observations (the SZ Infrared Experiment, SuZIE). Furthermore, Benson et al. (2003) estimated the bulk flow using six galaxy clusters at \(z > 0.2\) from the SuZIE II experiment in three frequency bands between 150 and 350 GHz, constraining the bulk flow to be \(< 1410 \text{ km s}^{-1}\) at 95% C.L. In addition, Kashlinsky & Attrio-Barandela (2000) and Kashlinsky et al. (2008, 2009) estimated peculiar velocities on large scales and claimed a “dark flow” \((\approx 1000 \text{ km s}^{-1})\) on Gpc scales. However, by combining galaxy cluster catalogues with Planck nominal mission foreground-cleaned maps, Planck Collaboration Int. XIII (2014) constrained the cluster velocity monopole to be \(72 \pm 60 \text{ km s}^{-1}\) and the dipole (bulk flow) to be \(< 254 \text{ km s}^{-1}\) (95% C.L.) in the CMB rest frame. This indicates that the Universe is largely homogeneous on Gpc scales, consistent with the standard cold dark matter (ΛCDM) scenario with adiabatic initial conditions.

This work represents the third contribution of the Planck Collaboration to the study of the kSZ effect. In Planck Collaboration Int. XIII (2014) we focused on constraining the monopole and dipole of the peculiar velocity field, which gives constraints on the large-scale inhomogeneity of the Universe. In the second paper, Planck Collaboration Int. XXXVII (2016), we calculated the pairwise moment of the kSZ effect and cross-correlated this with the reconstructed peculiar velocity field \(\langle \Delta T(\mathbf{r}) \rangle\), obtaining direct evidence of unbound gas outside the virial radii of the clusters. A follow-up paper modelled these results to reconstruct the baryon fraction and suggested that this unbound gas corresponds to all baryons surrounding the galaxies (Hernández-Monteagudo et al. 2015). Even though the large-scale bulk flow and monopole flow were not detected in Planck Collaboration Int. XIII (2014), the small-scale velocity dispersion in the nearby Universe, determined by the local gravitational potential field, might still be measurable. This is because the velocity of each galaxy comprises two components, namely the bulk flow components, which reflect the large-scale perturbations, and a small-scale velocity dispersion component, which reflects perturbations due to the local gravitational potential (see, e.g., Watkins et al. 2009; Feldman et al. 2010; Ma & Scott 2013, 2014). Therefore, although the bulk flow of the galaxy clusters is constrained to be less than \(254 \text{ km s}^{-1}\), the total velocity dispersion can still be large enough to be detected. With that motivation, in this paper we will look at a different aspect than in the previous two papers, namely focusing on 1-point statistics of Planck data to constrain the temperature and velocity dispersion due to the kSZ effect. This topic is relevant for large-scale structure, since the velocity dispersion that we are trying to measure can be used as a sensitive test for galaxy formation models (Ostriker 1980; Davies et al. 1983; Kormendy & Bender 1996; Kormendy 2001; MacMillan et al. 2006) and moreover, a numerical value for the small-scale dispersion often has to be assumed in studies of large-scale flows (e.g., Ma et al. 2011; Turnbull et al. 2012). Providing such a statistical test through Planck’s full-mission foreground-cleaned maps is the main aim of the present paper.

This paper is organized as follows. In Sect. 2, we describe the Planck CMB data and the X-ray catalogue of detected clusters of galaxies. In Sect. 3, we discuss the filter that we develop to convolve the observational map, and the statistical methodology that we use for searching for the kSZ temperature-dispersion signal. Then we present the results of our search along with relevant statistical tests. In Sect. 4, we discuss the astrophysical implications of our result, the conclusions being presented in the last section. Throughout this work, we adopt a spatially flat, ΛCDM cosmology model, with the best-fit cosmological parameters given by Planck Collaboration XIII (2016): \(\Omega_m = 0.309\); \(\Omega_{\Lambda} = 0.691\); \(n_s = 0.9608\); \(\sigma_8 = 0.809\); and \(h = 0.68\), where the Hubble constant is \(H_0 = 100h \text{ km s}^{-1} \text{ Mpc}^{-1}\).

2. Data description

2.1. Planck maps

2.1.1. Maps from the Planck Legacy Archive

In this work we use the publicly released Planck 2015 data\(^3\). The kSZ effect gives rise to frequency-independent temperature fluctuations that are a source of secondary anisotropies. The kSZ effect should therefore be present in all CMB foreground-cleaned products. Here we investigate the four Planck 2015 foreground-cleaned maps, namely the Commander, NILC, SEVEM, and SMICA maps. These are the outputs of four different component-separation algorithms (Planck Collaboration Int. XXXVII 2016) and have a resolution of \(\theta_{\text{FWHM}} = 5 \text{ arcmin}\). SMICA uses a spectral-matching approach, SEVEM adopts a template-fitting method to minimize the foregrounds, NILC is the result of an internal linear combination approach, and Commander uses a parametric, pixel-based Monte Carlo Markov chain technique to

---

\(^1\) Although in principle one could still have an isocurvature perturbation on very large scales (Turner 1991; Ma et al. 2011).

\(^2\) Planck (http://www.esa.int/Planck) is a project of the European Space Agency (ESA) with instruments provided by two scientific consortia funded by ESA member states and led by Principal Investigators from France and Italy, telescope reflectors provided through a collaboration between ESA and a scientific consortium led and funded by Denmark, and additional contributions from NASA (USA).

\(^3\) From the Planck Legacy Archive, http://pla.esac.esa.int
removes the tSZ effect, as required by the vector *w* of Eq. (5) for the ILC method to provide a CMB estimate that is perfectly known across the frequency channels. The 2D-ILC project out foregrounds (Planck Collaboration XII 2014; Planck Collaboration IX 2016; Planck Collaboration X 2015). All of these maps are produced with the intention of minimizing the foreground contribution, but there could nevertheless be some residual contamination from the tSZ effect, as well as other foregrounds (e.g., the Galactic kSZ effect, see Waelkens et al. 2008). We use the HEALPix package (Göschl et al. 2005) to visualize and manipulate the maps.

### 2.1.2. The 2D–ILC map

The 2D–ILC Planck CMB map has the additional benefit of being constructed to remove contamination from the tSZ effect, provided that the tSZ spectral energy distribution is perfectly known across the frequency channels. The 2D–ILC CMB map has been produced by taking the Planck 2015 data and implementing the “constrained ILC” method developed in Remazeilles et al. (2011a). This component-separation approach was specifically designed to cancel out in the CMB map any residual of the tSZ effect towards galaxy clusters by using spectral filtering, as we now describe.

For a given frequency band *i*, the Planck observation map *x* can be modelled as the combination of different emission components:

\[ x_i(\hat{f}) = a_i s_{\text{CMB}}(\hat{f}) + b_i s_{\text{tSZ}}(\hat{f}) + n_i(\hat{f}), \]  
(2)

where *s_{\text{CMB}}(\hat{f})* is the CMB temperature anisotropy at pixel *f*, *s_{tSZ}(\hat{f})* is the tSZ fluctuation in the same direction, and *n_i(\hat{f})* is a “nuisance” term including instrumental noise and Galactic foregrounds at frequency *i*. The CMB fluctuations scale with frequency through a known emission law parameterized by the vector *a*, with nine components, accounting for the nine *Planck* frequency bands. The emission law of the tSZ fluctuations is also known and can be parameterized by the scaling vector *b* in the *Planck* frequency bands. The kSZ signal is implicitly included in the CMB fluctuations, since CMB anisotropies and kSZ fluctuations share the same spectral signature.

Similar to the standard NILC method (Basak & Delabrouille 2012, 2013), the 2D–ILC approach makes a minimum-variance-weighted linear combination of the *Planck* frequency maps. Specifically \( \tilde{s}_{\text{CMB}}(\hat{f}) = w^\top x(\hat{f}) = \sum_{i=1}^{9} w_i x_i(\hat{f}) \), under the condition that the scalar product of the weight vector *w* and the CMB scaling vector *a* is equal to unity, i.e., \( \sum_{i=1}^{9} w_i a_i = 1 \), which guarantees the conservation of CMB anisotropies in the filtering. However, 2D–ILC (Remazeilles et al. 2011a) generalizes the standard NILC method by offering an additional constraint for the ILC weights to be orthogonal to the tSZ emission law *b*, while guaranteeing the conservation of the CMB component. The 2D–ILC CMB estimate is thus given by

\[ \tilde{s}_{\text{CMB}}(\hat{f}) = w^\top x(\hat{f}), \]  
(3)

such that the variance of Eq. (3) is minimized, with

\[ w^\top a = 1, \]  
(4)

\[ w^\top b = 0. \]  
(5)

Benefiting from the knowledge of the CMB and tSZ spectral signatures, the weights of the 2D–ILC are constructed in order to simultaneously yield unit response to the CMB emission law *a* (Eq. (4)) and zero response to the tSZ emission law *b* (Eq. (5)). The residual contamination from Galactic foregrounds and instrumental noise is controlled through the condition (Eq. (3)). The exact expression for the 2D–ILC weights was derived in Remazeilles et al. (2011a) by solving the minimization problem (Eqs. (3)–(5)):

\[ \tilde{s}_{\text{CMB}}(\hat{f}) = \left( b^\top C_{\text{tSZ}}^{-1} b \right)^{-1} \left( a^\top C_{\text{tSZ}}^{-1} a \right) \left( b^\top C_{\text{tSZ}}^{-1} \right) \left( a^\top C_{\text{tSZ}}^{-1} \right)^{-1} w^\top x(\hat{f}), \]  
(6)

where *C_{tSZ}^{ij} = \{ x_i x_j \} *are the coefficients of the frequency-frequency covariance matrix of the *Planck* channel maps; in practice we compute this locally in each pixel *p* as

\[ C_{tSZ}^{ij}(p) = \sum_{p \in \mathcal{D}(p)} x_i(p') x_j(p'). \]  
(7)

Here the pixel domain \( \mathcal{D}(p) \) (referred to as “super pixels”) around the pixel *p* is determined by using the following procedure: the product of frequency maps *x_i* and *x_j* is convolved with

<table>
<thead>
<tr>
<th>Method</th>
<th>Reference</th>
<th>kSZ data</th>
<th>Tracer type</th>
<th>Tracer data</th>
<th>Significance</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pairwise temperature difference</td>
<td>Planck Collaboration Int. XXXVII (2016)</td>
<td>Planck</td>
<td>Galaxies (spec-z)</td>
<td>S0/DSR7</td>
<td>2.9 σ</td>
</tr>
<tr>
<td>Planck</td>
<td>Planck</td>
<td>Galaxies (spec-z)</td>
<td>S0/DSR7</td>
<td>1.8–2.5 σ</td>
<td></td>
</tr>
<tr>
<td>Soergel et al. (2016)</td>
<td>Planck</td>
<td>Galaxies (spec-z)</td>
<td>S0/DSR7</td>
<td>3.3 σ</td>
<td></td>
</tr>
<tr>
<td>Hernández-Monteagudo et al. (2015)</td>
<td>WMAP</td>
<td>Galaxies (spec-z)</td>
<td>S0/DSR7</td>
<td>4.2 σ</td>
<td></td>
</tr>
<tr>
<td>De Bernardis et al. (2017)</td>
<td>SPT</td>
<td>Clusters (photo-z)</td>
<td>1-yr DES</td>
<td>3.6–4.1 σ</td>
<td></td>
</tr>
<tr>
<td>Sugiyama et al. (2018)</td>
<td>Planck</td>
<td>Galaxies (spec-z)</td>
<td>BOSS/DR1</td>
<td>2.45 σ</td>
<td></td>
</tr>
<tr>
<td>Li &amp; Pl외 (2018)</td>
<td>Planck</td>
<td>Galaxies (spec-z)</td>
<td>BOSS/DR10</td>
<td>1.65 σ</td>
<td></td>
</tr>
<tr>
<td>Planck × η_{spec}</td>
<td>Planck Collaboration Int. XXXVII (2016)</td>
<td>Planck</td>
<td>Galaxy velocities</td>
<td>SDSS/DR7</td>
<td>3.0–3.7 σ</td>
</tr>
<tr>
<td>Schaan et al. (2016)</td>
<td>Planck</td>
<td>Galaxy velocities</td>
<td>BOSS/DR10</td>
<td>2.9 σ, 3.3 σ</td>
<td></td>
</tr>
<tr>
<td>kSZ × projected density field</td>
<td>Hill et al. (2016)</td>
<td>Planck, Projected</td>
<td>WISE</td>
<td>3.8–4.5 σ</td>
<td></td>
</tr>
<tr>
<td>Ferraro et al. (2016)</td>
<td>WMAP</td>
<td>Projected overdensities</td>
<td>catalogue</td>
<td></td>
<td></td>
</tr>
<tr>
<td>kSZ^2 × projected density field</td>
<td>This work</td>
<td>Planck</td>
<td>Clusters</td>
<td>MCG</td>
<td>2.8 σ</td>
</tr>
</tbody>
</table>

Notes. “Spec-z” and “photo-z” mean galaxy surveys with spectroscopic or photometric redshift data, respectively. “DES” stands for Dark Energy Survey. (a) A *p*-value of 0.002 is quoted in the original paper, which we convert to S/N by using Eq. (C.3). (b) The differences between Sugiyama et al. (2018) and Li & Plavec (2018) are that the former used a Fourier-space analysis and a density-weighted pairwise estimator, while the latter used a real-space analysis and a uniform-weighting pairwise momentum estimator. (c) Galaxy peculiar velocities form SDSS/DR7 in Planck Collaboration Int. XXXVII (2016) and BOSS/DR10 in Schaan et al. (2016) are obtained by reconstructing the linear peculiar velocity field from the density field. (d) Here “kSZ^2” means the squared kSZ field.
a Gaussian kernel in pixel space in order to avoid sharp edges at the boundaries of super pixels that would create spurious power (Basak & Delabrouille 2012, 2013).

Before applying the 2D–ILC filter (Eq. (6)) to the Planck 2015 data, we first pre-process the data by performing point-source “in-painting” and wavelet decomposition, in order to optimize the foreground cleaning. In each Planck channel map we mask the point-sources detected at $S/N > 5$ in the Second Planck Catalogue of Compact Sources PCCS2 (Planck Collaboration XXVI 2016). The masked pixels are then filled in by interpolation with neighbouring pixels through a minimum curvature spline surface in-painting technique, as implemented in Remazeilles et al. (2015). This pre-processing of the point-source regions will guarantee reduction of the contamination from compact foregrounds in the kSZ measurement.

The in-painted Planck maps are then decomposed into a particular family of spherical wavelets called “needlets” (see, e.g., Narcowich et al. 2006; Guilloux et al. 2009). The needlet transform of the Planck maps is performed as follows. The spherical harmonic coefficients $a_{\ell m}$ of the Planck channel maps $\chi_i$ are bandpass filtered in multipole space in order to isolate the different ranges of angular scales in the data. The 2D–ILC weights (Eq. (6)) are then computed in pixel space from the inverse spherical harmonic transform of the bandpass-filtered $a_{\ell m}$ coefficients. The frequency-frequency covariance matrix in Eq. (7) is actually computed on the bandpass-filtered maps. In this way, component separation is performed for each needlet scale (i.e., range of multipoles) independently. Due to their localization properties, the needlets allow for a filtering in both pixel space and multipole space, therefore adapting the component-separation procedure to the local conditions of contamination in both spaces (see Delabrouille et al. 2009; Remazeilles et al. 2011b; Basak & Delabrouille 2012, 2013).

The top left panel of Fig. 1 shows the result of stacking 3° × 3° patches of the NILC Planck CMB map in the direction of known galaxy clusters, while the top right panel shows the result of stacking the 2D–ILC Planck CMB map in the direction of the same set of galaxy clusters4. The Planck SZ sample provides a very stringent test, because these are the places on the sky where Planck detected a significant $y$ signature. We see that stacking of the NILC CMB map shows a significant tSZ residual effect in the direction of galaxy clusters. Conversely, the stacking of the 2D–ILC Planck CMB map (right panel of Fig. 1) appears to show substantially reduced tSZ residuals, due to the 2D–ILC filtering. In the bottom panels of Fig. 1 we show the results of the stacking procedure for the specific cluster catalogue that we will be using for the main analysis in this paper (see next section for details).

The profiles of the stacked patches are plotted in Fig. 2. The excess of power due to tSZ residuals in the NILC CMB map would clearly lead to a significant bias in any attempt to detect the kSZ signal at the positions of the galaxy clusters. As a baseline reference, the flux profile of the Planck 217-GHz map, stacked in the directions of these galaxy clusters, is also plotted in Fig. 2 (green squares). The tSZ signal should in principle vanish in observations at 217 GHz, since that is effectively the null frequency for the tSZ signature; in practice it is non-zero in the Planck 217-GHz map because of the broad spectral bandpass. In fact there is an offset of about 20 µK in the flux profile of the stacked 217-GHz map at the position of PSZ clusters. There is also still a residual offset in the 2D–ILC CMB map; however, it is smaller by a factor of about 2 than the tSZ signal in the baseline Planck 217-GHz map (see top panel of Fig. 2), and dramatically better than for the NILC map. This suggests that the method employed for the 2D–ILC map was successful in removing the tSZ signal.

The residual flux of the stacked 2D–ILC CMB map in the direction of galaxy clusters can be interpreted as the result of possibly imperfect assumptions in the 2D–ILC filter and the exact tSZ spectral shape across the Planck frequency bands. There may be several reasons behind incomplete knowledge of the tSZ spectrum: detector bandpass mismatch; calibration uncertainties; and also relativistic tSZ corrections. In addition, even if the kSZ flux is expected to vanish on average when stacking inward- and outward-moving clusters in a homogeneous universe, there is still a potential selection bias (since we use a selected subset of clusters for stacking) that may result in a non-zero average kSZ residual in the offset of the 2D–ILC map. Although it is not easy to estimate the size of all these effects, we are confident that they cannot be too large because the residual offset in the 2D–ILC map is negligible compared to the tSZ residuals in Planck CMB maps, and smaller by a factor of 2 with respect to the baseline Planck 217-GHz map.

Regarding residual Galactic foreground contamination, we checked that the angular power spectrum of the 2D–ILC CMB map on the 60% of the sky that is unmasked is consistent with the angular power spectrum of the Planck SMICA CMB maps. There is therefore no obvious excess of power due to Galactic emission. We also checked the amount of residual dust contamination of the kSZ signal on small angular scales in the direction of the galaxy clusters, where dusty star-forming galaxies are present (Planck Collaboration Int. XLIII 2016). Considering the Planck 857-GHz map as a dust template, we scaled it across the

---

4 The Planck PSZ1 catalogue of galaxy clusters from the 2013 Planck data release has been used to determine the position of known SZ clusters.
of each stable pointing period (also called “rings”). In the half-difference of the resulting “first” and “second” 2D–ILC maps, the sky emission cancels out, therefore leaving an estimate of the noise contamination in the 2D–ILC CMB maps, constructed from the full-survey data set.

The 2D–ILC CMB map shows approximately 10% more noise than the NILC CMB map; this arises from the additional constraint imposed in the 2D–ILC of cancelling out the tSZ emission. At the cost of having a slightly higher noise level, the 2D–ILC CMB map benefits from the absence of bias due to tSZ in the directions of galaxy clusters. For this reason, the 2D–ILC CMB map is particularly well suited for the extraction of the kSZ signal in the direction of galaxy clusters and we shall focus on it for the main results of this paper.

2.2. The MCXC X-ray catalogue

To trace the underlying baryon distribution, we use the Meta Catalogue of X-ray detected Clusters of galaxies (MCXC), which is an all-sky compilation of 1743 all-sky ROSAT survey-based samples (BCS, Ebeling et al. 1998, 2000; CIZA, Ebeling et al. 2010; Kocevski et al. 2007; MACS, Ebeling et al. 2007; NEP, Henry et al. 2006; NORAS, Böhringer et al. 2000; REFLEX, Böhringer et al. 2004; SCP, Cruciani et al. 2002) along with a few other catalogues (160SD, Mullis et al. 2003; 400SD, Burenin et al. 2007; EMSS, Gioia & Luppino 1994; Henry 2004; SHARC, Romer et al. 2000; Burke et al. 2003; WARPS, Perlman et al. 2002; Hornor et al. 2008). We show stacks and profiles for this catalogue on the Planck map in Figs. 1 and 2. While selecting sources from this catalogue, we use the luminosity within $R_{500}$ (the radius of the cluster within which the density is 500 times the cosmic critical density), $L_{500}$, and restrict the samples to have $1.5 \times 10^{35} \text{W} < L_{500} < 3.7 \times 10^{38} \text{W}$ within the band 0.1–2.4 keV (see Piffaretti et al. 2011). As well as $L_{500}$, for each cluster the catalogue gives $M_{500}$, the mass enclosed within $R_{500}$ at redshift $z$, i.e., $M_{500} = (4\pi/3)500 \rho_c(z) R_{500}^3$, estimated using the empirical relation $L_{500} \propto M_{500}^{0.64}$ in Arnaud et al. (2010). Further details of catalogue homogenization and calibration are described in Piffaretti et al. (2011) and Planck Collaboration Int. XIII (2014).

For each cluster in the MCXC catalogue, the properties we use in the rest of this paper are the sky position (Galactic coordinates $l$, $b$), the redshift $z$, and the mass $M_{500}$. In Sect. 4 we will use $M_{500}$ and $z$ to estimate the optical depth for each cluster.

Since in the CMB map, the Galactic plane region is highly contaminated by foreground emission, we use the Planck Galactic and point-source mask to remove 40% of the sky area. The number of MCXC sources outside the sky mask is $N_s = 1526$ (which we use throughout the paper) and their spatial and redshift distributions are shown in Fig. 3. The full-sky distribution is presented in the left panel of Fig. 3, and one can see that the distribution of MCXC clusters is roughly uniform outside the Galactic mask. The redshift of MCXC clusters peaks at $z = 0.09$, with a long tail towards higher redshift, $z \gtrsim 0.4$.

3. Methodology and statistical tests

3.1. Matched-filter technique

The foreground-cleaned CMB maps (SEVEM, SMICA, NILC, Commander, and 2D–ILC) contain mainly the primary CMB and kSZ signals, so in order to optimally characterize the kSZ signal, we need to use a spatial filter to convolve the maps in order

![Graph](image-url)
to downweight the CMB signal. Here we use the matched-filter technique (e.g., Tegmark & de Oliveira-Costa 1998; Ma et al. 2013), which is an easily implemented approach for suppressing the primary CMB and instrumental noise.

Most of Planck’s SZ-clusters are unresolved, so we treat them as point sources on the sky. In this limit, if cluster $i$ has flux $S_i$, at sky position $\hat{r}_i$, the sky temperature $\Delta T(\hat{r})$ can be written as

$$\Delta T(\hat{r}) = c \sum_j S_j \delta_\text{D}(\hat{r}, \hat{r}_j) + \sum_{lm} a_{lm} Y_{lm}(\hat{r}),$$

where $\delta_\text{D}$ is the Dirac delta function, $c$ is the conversion factor between flux and temperature, and the spherical harmonics characterize the true CMB fluctuations. The sky signal, obtained from the Planck telescope, is

$$\Delta T^\text{obs}(\hat{r}) = c \sum_j S_j \left( \sum_\ell \frac{2\ell + 1}{4\pi} P_\ell(\hat{r} \cdot \hat{r}_j) B_\ell \right) + \sum_{lm} a_{lm}^\text{noise} Y_{lm}(\hat{r}),$$

where $a_{lm}^\text{noise}$ is the true CMB signal convolved with the beam plus the detector noise, i.e., $a_{lm}^\text{noise} = B_\ell a_{lm}^\text{CMB} + n_{lm}$ (assuming that this is the only source of noise). The beam function of Planck foreground-cleaned maps in $\ell$-space is close to a Gaussian with $\theta_{\text{FWHM}} = 5$ arcmin, i.e., $B_\ell = \exp(-\ell^2 \sigma^2_{\text{FWHM}})$, with $\sigma_{\text{FWHM}} = \sqrt{8} \ln 2$. Residual foregrounds in the Planck CMB maps and in the 2D-ILC CMB map have been minimized in the component-separation algorithms, as demonstrated in Planck Collaboration IX (2016) for the public Planck CMB maps and in Planck Collaboration XIII (2014) for the 2D-ILC CMB map. Figure 4 compares the angular power spectrum, $C_\ell$, directly estimated from the map by using the pseudo-$C_\ell$ estimator (Hivon et al. 2002), and the spectrum predicted by using the best-fit $\Lambda$CDM model and noise template. One can see that the measured spectral data scatter around the predicted spectrum, and that the two spectra are quite consistent with each other.

In order to maximize our sensitivity to SZ clusters, we further convolve $\Delta T^\text{obs}(\hat{r})$ with an optimal filter $W_\ell$:

$$\Delta T'(\hat{r}) = c \sum_j S_j \left( \sum_\ell \frac{2\ell + 1}{4\pi} P_\ell(\hat{r} \cdot \hat{r}_j) B_\ell W_\ell \right) + \sum_{lm} a_{lm}^\text{noise} W_\ell Y_{lm}(\hat{r}),$$

where we are seeking the form of $W_\ell$ that will maximize cluster S/N. In the direction of each cluster, the filtered signal is

$$\Delta T_\ell(\hat{r}_j) = c S_j \left( \sum_\ell \frac{2\ell + 1}{4\pi} B_\ell W_\ell \right) \equiv (c S_j) A,$$

and we want to vary $W_\ell$ to minimize the ratio

$$\sigma^2 = \frac{\text{Var} \left( \frac{\Delta T_\ell}{A} \right)}{\left( \sum_\ell \frac{2\ell + 1}{4\pi} C_\ell^\text{noise} W_\ell^2 \right)^2},$$

where $C_\ell^\text{noise} = B_\ell^2 C_\ell^\text{CMB} + N_\ell$, and we take $C_\ell^\text{CMB}$ to be the $\Lambda$CDM model power spectrum. Since $A$ in Eq. (11) is a constant, we minimize Eq. (12) by adding a Lagrange multiplier to the numerator (see, e.g., Ma et al. 2013), i.e., we minimize

$$\sum_\ell \frac{2\ell + 1}{4\pi} C_\ell^\text{noise} W_\ell^2 - \lambda \left( \sum_\ell \frac{2\ell + 1}{4\pi} B_\ell W_\ell \right)^2.$$

We then obtain

$$W_\ell = \frac{B_\ell}{B_\ell^2 C_\ell^\text{CMB} + N_\ell} = \frac{B_\ell}{C_\ell^\text{noise}},$$

where $\lambda$ is the Lagrange multiplier.
which we plot in Fig. 5 as a black line, along with the primary CMB $C_\ell$, the noise map, and their sum. In the filtering process, we use the normalized filter $W_{\text{nor}} = W_{\ell}/\bar{W}$, where $\bar{W} = \sum_{\ell=1}^{\ell_{\text{max}}} W_{\ell}/\ell_{\text{max}}$. One can see that the filter function $W_\ell$ gives lower weight in the primary CMB domain while giving more weight in the cluster regime, $\ell \gtrsim 2000$. We then convolve the five Planck foreground-cleaned maps with this $W_\ell$ filter, noting that the noise power spectrum $N_\ell$ in Eq. (14) of each foreground-cleaned map is estimated by using its corresponding noise map. After we perform this step, the primary CMB features are highly suppressed (Fig. 6), and the whole sky looks essentially like a noisy map, although it still contains the kSZ information of course.

### 3.2. Statistical method and tests of robustness

We now proceed to estimate the kSZ temperature dispersion and perform various tests. The filtered map contains the kSZ signal and residual noise, and from this we plot the histogram of $1526 \Delta T/T$ values at the cluster positions (see red bars in Fig. 7). We can also randomly select the same number of pixels on the sky and plot a histogram for that. The two histograms have almost zero mean value (Table 2), but in the real cluster positions yield a larger variance than the random selections, i.e., the real cluster positions give a slightly broader distribution than for the randomly selected positions (Table 2). We also show results for the skewness and kurtosis of the two samples in Table 2, and one can see that for these statistics the real cluster positions also give larger values than for the randomly-selected positions. This suggests that there may be additional tests that could be performed to distinguish the real cluster kSZ signals; however, we leave that for future studies, and for the rest of this paper we just focus on investigating whether the slight broadening of the distribution is due to the kSZ effect.

#### 3.2.1. Test of thermal Sunyaev-Zeldovich effect residuals

The first test we want to perform is to check whether the measured kSZ $\langle \Delta T/T \rangle$ value at each cluster position suffers from residuals of the tSZ effect. The mapmaking procedures of SMICA, NILC, SEVEM, and Commander minimize the variance of all non-CMB contribution to the map, but they are not designed to null the tSZ component. By contrast, the 2D–ILC map is designed to also null the tSZ contribution, and therefore should provide a cleaner measurement of the kSZ effect (but with a slightly higher noise level).

We first choose 5000 randomly selected catalogues from each Planck foreground-cleaned map, each being a collection of 1526 random positions on the sky. We then convolve the five Planck foreground-cleaned maps with this $W_\ell$ filter, noting that the noise power spectrum $N_\ell$ in Eq. (14) of each foreground-cleaned map is estimated by using its corresponding noise map. After we perform this step, the primary CMB features are highly suppressed (Fig. 6), and the whole sky looks essentially like a noisy map, although it still contains the kSZ information of course.
suggests that at each of the true cluster positions the (\(\Delta T/T\)) value contains some contribution from the tSZ effect, so that the tSZ effect contributes extra variance to the foreground-cleaned maps.

We then calculate the average value of (\(\Delta T/T\)) at the true cluster positions for the five Planck foreground-cleaned maps as the vertical bars in Fig. 8. One can see that only the average (\(\Delta T/T\)) value of the 2D–ILC map lies close to zero and within the 68% width of the noise histogram, while the values of all other maps are quite far from the centre of the noise distribution. This strongly suggests that at each of the true cluster positions the (\(\Delta T/T\)) value contains some contribution from the tSZ effect, so that the tSZ effect contributes extra variance to the foreground-cleaned maps.

In Table 3, we list the rms value for the true sky positions of the 1526 true MCXC position is 1.17 × 10^{-5}, larger than the mean value at more than the 3 \(\sigma\) level. In Table 3, we list the rms value for the true sky positions of the 1526 MCXC catalogue sources (\(\sigma_{\text{MCXC}}\)), the mean (\(\sigma_{\text{ran}}\)), and standard deviation (\(\sigma(\sigma_{\text{ran}})\)) for 5000 random catalogue sources (\(\sigma(\sigma_{\text{ran}})\)). This consistency strongly suggests that the kSZ effect contributes to the extra dispersion in the convolved (\(\Delta T/T\)) maps at the cluster positions (since the 2D–ILC map is constructed to remove the tSZ effect). If we use the SMICA, SEVEM, NILC, and Commander maps, the detailed values will vary slightly due to the different calibration schemes of the maps, but the detection remains consistently there. The difference between \(\sigma_{\text{MCXC}}\) and \(\sigma_{\text{ran}}\) is slightly larger in the SMICA, NILC, and SEVEM maps due to residual tSZ contamination, shown as the vertical bars in Fig. 8.

This all points towards the broadening of the (\(\Delta T/T\)) histogram being a consequence of the kSZ effect; hence we identify it as additional temperature dispersion arising from the scatter in cluster velocities detected through the kSZ effect. In Sect. 4, we will interpret this effect in terms of the line-of-sight velocity

\[ \frac{\Delta T}{T} = \frac{\sum (\Delta T_i/T_i)}{N} \times 10^7 \]

where \(N\) is the number of maps.

\[ [Nc^{-1}\sum_i (\Delta T_i/T)] \times 10^7 \]

and 2.62 × 10^{-7}, respectively. This indicates that the noise level in the filtered 2D–ILC map is slightly higher than for the other four maps.

We then calculate the average value of (\(\Delta T/T\)) at the true cluster positions for the five Planck foreground-cleaned maps as the vertical bars in Fig. 8. One can see that only the average (\(\Delta T/T\)) value of the 2D–ILC map lies close to zero and within the 68% width of the noise histogram, while the values of all other maps are quite far from the centre of the noise distribution. This strongly suggests that at each of the true cluster positions the (\(\Delta T/T\)) value contains some contribution from the tSZ effect, so that the tSZ effect contributes extra variance to the foreground-cleaned maps.

\[ \frac{\Delta T}{T} = \frac{\sum (\Delta T_i/T_i)}{N} \times 10^7 \]

where \(N\) is the number of maps.

\[ [Nc^{-1}\sum_i (\Delta T_i/T)] \times 10^7 \]
dispersion of the SZ clusters, which is an extra variance predicted in linear perturbation theory in the standard picture of structure formation (Peebles 1980).

### 3.2.3. Test with finite cluster size

We now want to test how much our results depend on the assumption that SZ clusters are point sources. A cluster on the sky appears to have a radius of $\theta_{500}$, which is equal to $\theta_{500} = R_{500}/D_A$, where $R_{500}$ is the radius from the centre of the cluster at which the density contrast is equal to 500 and $D_A$ is the angular diameter distance to the cluster. The peak in the distribution of $\theta_{500}$ values for the MCXC clusters lies around 3 arcmin, so we multiply the filter function (Eq. (14)) with an additional “cluster beam function” $B_\mathrm{c} = \exp(-t^2\theta_{500}^2/2)$, where $\sigma_\theta = \theta_{500}/\sqrt{8\ln 2}$. We pick three different values for the cluster size, namely $\theta_{500} = 3$, 5, and 7 arcmin, and see how our results change.

We list our findings in Table 4; one can see that the detailed values for three cases are slightly different from those of the point-source assumptions, but the changes are not dramatic. More importantly, the offsets between $\sigma_{\text{MCXC}}$ and $\sigma_{\text{ran}}$ stay the same for various assumptions of cluster size. Therefore the detection of the temperature dispersion due to the kSZ effect does not strongly depend on the assumption of clusters being point sources.

### 3.3. Statistical results

#### 3.3.1. Statistics with the uniform weight

We now want to perform a more quantitative calculation of the significance of detection. Since the convolved map mainly consists of the kSZ signal at the cluster positions plus residual noise, we write the observed temperature fluctuation at the cluster positions as

$$\frac{\Delta T}{T} \equiv \delta = s + n,$$

where $\delta$, $s$, and $n$ represent the observed $\Delta T/T$ value, the kSZ signal contribution, and the residual noise, respectively, all of which are dimensionless quantities. Now we define the estimator $s^2$ as

$$s^2 = \frac{1}{N_c} \sum_i \delta_i^2 - \frac{1}{N_c} \sum_i n_i^2,$$

where the summation includes all of the $N_c = 1526$ cluster positions. For the first term $\delta_i$, we use the $N_c$ true cluster position as the measurement of each observed $\Delta T/T$. For the second term, we randomly select $N_c$ pixels outside the Galactic and point-source mask that are not cluster positions. The calculation of the first term is fixed, whereas the second term depends on the $N_c$ random positions we choose. Each randomly selected set of $N_c$ positions corresponds to a mock catalogue, which leads to one value of $s^2$. We do this for 5000 such catalogues, where each mock catalogue has a different noise part ($\delta_i$) in Eq. (16), but the same observed $\delta_i$. Then we plot the histogram of $s^2$ values for these catalogues in the left panel of Fig. 10. One can see that the $s^2$ distribution is close to a Gaussian distribution with mean and error being $s^2 = (1.64 \pm 0.48) \times 10^{-11}$.

One can use a complementary method to obtain the mean and variance of $s^2$, i.e., $E[s^2]$ and $V[s^2]$. We lay out this calculation in Appendix A, where we directly derive these results:

$$E[s^2] = \bar{\delta}^2 - \mu_2(n);$$

$$V[s^2] = \frac{1}{N_c} \left[ \mu_4(n) - \bar{\delta}^2 - \mu_2(n) \right].$$

(17)

Here $\mu_2$ and $\mu_4$ are the second and fourth moments of the corresponding random variables.

For the moments of $\delta$, we use the measurements at the 1526 cluster positions. For the estimate of the noise, we take all of the unmasked pixels of the convolved sky. In order to avoid selecting the real cluster positions, we remove all pixels inside a 10 arcmin aperture around each cluster. These “holes” at cluster positions constitute a negligible portion of the total unmasked pixels, and our results are not sensitive to the aperture size we choose. As a result, we have approximately $3 \times 10^7$ unmasked pixels to sample the noise. We then substitute the values into Eq. (17) to obtain the expectation values and variances.

In Table 5, we list the mean and rms value of $\bar{s}^2$. Comparing with the 2D–ILC map, one can see that the SMICA, NILC, and SEVEM maps give larger values of $E[s^2]$ and therefore apparently higher significance levels, which we believe could be due to the fact that the residual tSZ effect in these maps contributes to the signal. However, the Commander map gives a reasonable estimate of the dispersion, since it appears to be less contaminated by tSZ residuals (see Fig. 8). As discussed in Sect. 2.1.2, the mapmaking procedure of the 2D–ILC product enables us to null the tSZ effect so that the final map should be free of tSZ, but with larger noise. This is the reason that we obtain a somewhat lower significance in Table 5 for 2D–ILC compared to some of the other maps. We will therefore mainly quote this conservative detection in the subsequent analysis.

#### 3.3.2. Statistics with different weights

The results so far have been found using the same weights for each cluster position. We now examine the stability of the detection using weighted stacking. In Eq. (16) we defined stacking

<table>
<thead>
<tr>
<th>Map</th>
<th>$\sigma_{\text{MCXC}} \times 10^5$</th>
<th>$\sigma_{\text{ran}} \times 10^5$</th>
<th>$\sigma(\sigma_{\text{ran}}) \times 10^5$</th>
</tr>
</thead>
<tbody>
<tr>
<td>2D–ILC</td>
<td>1.17</td>
<td>1.10</td>
<td>0.022</td>
</tr>
<tr>
<td>SMICA</td>
<td>1.11</td>
<td>0.97</td>
<td>0.019</td>
</tr>
<tr>
<td>NILC</td>
<td>1.09</td>
<td>0.97</td>
<td>0.019</td>
</tr>
<tr>
<td>SEVEM</td>
<td>1.12</td>
<td>1.00</td>
<td>0.020</td>
</tr>
<tr>
<td>Commander</td>
<td>1.09</td>
<td>1.03</td>
<td>0.020</td>
</tr>
</tbody>
</table>

### Table 3.

rms values for the true sky positions of 1526 MCXC catalogue clusters ($\sigma_{\text{MCXC}}$), along with the mean ($\sigma_{\text{ran}}$) and scatter ($\sigma(\sigma_{\text{ran}})$) of the values of the rms for 5000 random catalogues, where each catalogue consists of 1526 random positions on the sky.

<table>
<thead>
<tr>
<th>Map</th>
<th>$\sigma_{\text{MCXC}} \times 10^5$</th>
<th>$\sigma_{\text{ran}} \times 10^5$</th>
<th>$\sigma(\sigma_{\text{ran}}) \times 10^5$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Point source</td>
<td>1.17</td>
<td>1.10</td>
<td>0.022</td>
</tr>
<tr>
<td>3 arcmin</td>
<td>1.19</td>
<td>1.12</td>
<td>0.022</td>
</tr>
<tr>
<td>5 arcmin</td>
<td>1.26</td>
<td>1.19</td>
<td>0.023</td>
</tr>
<tr>
<td>7 arcmin</td>
<td>1.42</td>
<td>1.36</td>
<td>0.026</td>
</tr>
</tbody>
</table>

### Table 4.

Same as Table 3 for the 2D–ILC map, but changing the assumed size of the clusters in the filtering function (Eq. (14)).
We have tested with 50 000 values of $s^2$ and the results are consistent with those from 5000 values.

Table 5. Statistics of the variables $\tilde{s}^2$ due to the kSZ effect for different CMB maps.

<table>
<thead>
<tr>
<th>Map</th>
<th>$E[s^2] \times 10^{11}$</th>
<th>$\langle V[s^2] \rangle^{1/2} \times 10^{11}$</th>
<th>S/N</th>
</tr>
</thead>
<tbody>
<tr>
<td>2D–ILC</td>
<td>1.64</td>
<td>0.48</td>
<td>3.4</td>
</tr>
<tr>
<td>SMICA</td>
<td>3.53</td>
<td>0.37</td>
<td>9.4</td>
</tr>
<tr>
<td>NILC</td>
<td>2.75</td>
<td>0.38</td>
<td>7.3</td>
</tr>
<tr>
<td>SEVEM</td>
<td>3.19</td>
<td>0.40</td>
<td>8.1</td>
</tr>
<tr>
<td>Commander</td>
<td>1.47</td>
<td>0.42</td>
<td>3.5</td>
</tr>
</tbody>
</table>

with uniform weights, which can be generalized to

$$\tilde{s}_{w}^2 = \frac{\sum (\delta_i^2 - \tilde{\delta}_{i}) w_i}{\sum w_i},$$  \hspace{1cm} (18)

where $w_i$ is the weight function. We certainly expect “larger” clusters to contribute more to the signal, but it is not obvious what cluster property will be best to use. In Table 6, we try different weighting functions $w_i$, with the first row being the uniform weight, which is equivalent to Eq. (16). In addition, we try as different choices of weighting function the optical depth $\tau$ and its square $\tau^2$, the angular size $\theta_{500}$ and its square $\theta_{500}^2$, the luminosity $L_{500}$ and its square $L_{500}^2$, and the mass $M_{500}$ and its square $M_{500}^2$. Since some of these may give distributions of $s_{w}^2$ that deviate from Gaussians, we also calculate the frequencies for finding $s_{w}^2$ smaller than zero, $P(s_{w}^2 < 0)$. The smaller this $P$-value is, the more significant is the detection.

From Table 6, we see that most weighting choices are consistent with uniform weighting though with reduced significance of the detection, the exceptions being the choices of $\tau_{500}$ or $\theta_{500}^2$. For $w_i = \theta_{500}$ and $w_i = \theta_{500}^2$, we have $P$-values of 0.0002 and 0.0039, respectively, yielding (1-sided) significance levels of 3.5 $\sigma$ and 2.7 $\sigma$. Their distributions deviate slightly from a Gaussian, with a tail toward smaller values.

The increased detection of excess variance using $\theta_{500}$ weighting stems from our choice of using a single cluster beam function for all clusters. In Sect. 3.2.3 we tested the robustness of our results to the choice of cluster beam function, finding little dependence. Nevertheless, such a test assumed all clusters had the same angular size, while in reality there is a large spread in the angular sizes of the clusters. By weighting with $\theta_{500}$ we are able to recover some of this lost signal in a quick and simple way, which we tested by comparing results for larger clusters versus smaller clusters. Despite this, we find that the increased significance is mainly due to the increased value for $E[s^2]$ and not a decrease in the noise. This tension may be evidence of systematic effects in the data or potentially some noise coming from residual tSZ signal in the 2D–ILC map; this should be further investigated when better data become available.

Table 6. Statistics of the weighted variables $\tilde{s}_{w}^2$ for different choices of weights in the 2D–ILC map.

<table>
<thead>
<tr>
<th>Weight</th>
<th>$E[s_{w}^2] \times 10^{11}$</th>
<th>$\langle V[s_{w}^2] \rangle^{1/2} \times 10^{11}$</th>
<th>$P(s_{w}^2 &lt; 0)$</th>
<th>S/N</th>
</tr>
</thead>
<tbody>
<tr>
<td>Uniform</td>
<td>1.64</td>
<td>0.48</td>
<td>0.07%</td>
<td>3.2</td>
</tr>
<tr>
<td>$\tau$</td>
<td>1.65</td>
<td>0.50</td>
<td>0.11%</td>
<td>3.1</td>
</tr>
<tr>
<td>$\tau^2$</td>
<td>1.62</td>
<td>0.55</td>
<td>0.38%</td>
<td>2.7</td>
</tr>
<tr>
<td>$\theta_{500}$</td>
<td>3.33</td>
<td>0.64</td>
<td>0.02%</td>
<td>3.5</td>
</tr>
<tr>
<td>$\theta_{500}^2$</td>
<td>6.86</td>
<td>1.72</td>
<td>0.39%</td>
<td>2.7</td>
</tr>
<tr>
<td>$L_{500}$</td>
<td>1.34</td>
<td>0.91</td>
<td>6.94%</td>
<td>1.5</td>
</tr>
<tr>
<td>$L_{500}^2$</td>
<td>0.65</td>
<td>2.15</td>
<td>32.4%</td>
<td>0.5</td>
</tr>
<tr>
<td>$M_{500}$</td>
<td>1.91</td>
<td>0.65</td>
<td>0.43%</td>
<td>2.6</td>
</tr>
<tr>
<td>$M_{500}^2$</td>
<td>1.81</td>
<td>1.36</td>
<td>8.75%</td>
<td>1.4</td>
</tr>
</tbody>
</table>

Notes. We use both linear and squared weights for each of optical depth, luminosity, mass, and $\theta_{500} = R_{500}/D_A$, where $D_A$ is the angular diameter distance of the cluster. The third column lists the frequency $P(s_{w}^2 < 0)$ of finding a value of $s_{w}^2$ smaller than zero, and the fourth column lists the equivalent S/N ratio (see Appendix C).
as defined in Eq. (16) for the two sub-samples and list our results in Table 7.

We see that the groups with lower values of $L_{500}$, $M_{500}$, and $R_{500}$ give detections of the $\kSZ$ temperature dispersion at 1.1$\sigma$, 1.2$\sigma$, and 0.7$\sigma$, whereas the higher value subsets give higher $S/N$ detections. It is clear that the signal we see is dominated by the larger, more massive, and more luminous subset of clusters, as one might expect. In principle one could use this information (and that of the previous subsection) to devise an estimator that takes into account the variability of cluster properties in order to further maximize the $\kSZ$ signal; however, a cursory exploration found that, for our current data, improvements will not be dramatic. We therefore leave further investigations for future work.

### 3.4. Effect of lensing

An additional effect that could cause a correlation between our $\tSZ$-free CMB maps and clusters comes from gravitational lensing (as discussed in Ferraro et al. 2016). It is therefore important to determine what fraction of our putative $\kSZ$ signal might come from lensing, and we estimate this in the following way. The MCMX CMB temperature variance is set by the integrated local CMB power spectrum at these positions. Lensing by the clusters magnifies the CMB, locally shifting scales with respect to the global average, potentially introducing a lensing signal in the variance shift. If we were to compare the CMB variance between cluster lensed and unlensed skies unlimited by resolution, no difference would be seen; lensing is merely a remapping of points on the sky, and hence does not affect one-point measures, with local shifts in scales in the power spectrum being compensated by subtle changes in amplitude, keeping the variance the same. However, as noted by Ferraro et al. (2016), the presence of finite beams and of the filtering breaks this invariance and the relevance of the lensing effects needs to be assessed. Crudely, the cluster-lensing signal $\sigma \cdot \nabla T$ (with $\sigma$ the deflection due to the cluster) can be as large as 5$\mu$K (Lewis & Challinor 2006), hence potentially contributing $\approx 25\mu$K$^2$ to the observed variance $\hat{\sigma}^2 = (121 \pm 35)\mu$K$^2$, i.e., around the 1$\sigma$ level.

We obtain a more precise estimate with a CMB simulation as follows. After generating a Gaussian CMB sky with lensed CMB spectra, we lens the CMB at each cluster position according to the deflection field predicted for a standard halo profile (Navarro et al. 1996; Dodelson 2004) of the observed redshift and estimated mass. We use for this operation a bicubic spline interpolation scheme, on a high-resolution grid of 0.4 arcmin ($N_{\text{side}} = 8192$), using the python lensing tools\footnote{Available at https://github.com/carronj//LensIt}. We then add the 2D-ILC noise-map estimate to the CMB. We can finally compare the temperature variance at the cluster positions before and after cluster lensing. We show our results in Fig. 12. The background (yellow) histogram shows the value of the dispersion of the 5000 random catalogues on the simulated map with 2D-ILC noise added. The purple (red) line indicates the value of dispersion of the map without (with) cluster lensing added. One can see that with cluster lensing added the value of dispersion is shifted to a higher value by 1.4$\times$10$^{-5}$, which is somewhat less than the rms of the random catalogue (2.1$\times$10$^{-5}$). This indicates that the lensing causes a roughly 0.7$\sigma$ shift in the width of histogram. From Fig. 12, we can calculate the lensing-shifted $\hat{\sigma}^2$ as

$$\begin{align*}
\hat{\sigma}^2_{\text{lens}} &= \left(1.061 \times 10^{-5}\right)^2 - \left(1.047 \times 10^{-5}\right)^2 \\
&= 2.95 \times 10^{-12}. \tag{19}
\end{align*}$$

Therefore, using uniform weights, by subtracting the $\hat{\sigma}^2_{\text{lens}}$, the temperature dispersion $\hat{\sigma}^2$ in the 2D–ILC map is measured to be

$$\hat{\sigma}^2 = (1.35 \pm 0.48) \times 10^{-11}, \tag{20}$$

which is thus detected at the 2.8$\sigma$ level.

![Fig. 11. Left: $R_{500}$ versus $M_{500}$ for the sample. Right: $L_{500}$ versus $M_{500}$ for the sample. The vertical and horizontal lines show the median values of $R_{500}$, $M_{500}$, and $L_{500}$.](image)

Table 7. Statistics of split samples. Here the median values of the samples are ($M_{500})_{\text{mid}} = 1.68 \times 10^{14} M_\odot$, ($L_{500})_{\text{mid}} = 2.3 \times 10^{10} L_\odot$, and ($R_{500})_{\text{mid}} = 0.79$ Mpc.

<table>
<thead>
<tr>
<th>Criterion</th>
<th>$E[\sigma^2_{\omega}]$</th>
<th>$\left(V[\sigma^2_{\omega}]\right)^{1/2}$</th>
<th>$P(\sigma_{\omega} &lt; 0)$</th>
<th>$S/N$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$L_{500} &lt; (L_{500})_{\text{mid}}$</td>
<td>0.78</td>
<td>0.68</td>
<td>12.7%</td>
<td>1.1</td>
</tr>
<tr>
<td>$L_{500} &gt; (L_{500})_{\text{mid}}$</td>
<td>2.48</td>
<td>0.68</td>
<td>0.07%</td>
<td>3.2</td>
</tr>
<tr>
<td>$M_{500} &lt; (M_{500})_{\text{mid}}$</td>
<td>0.83</td>
<td>0.68</td>
<td>11.4%</td>
<td>1.2</td>
</tr>
<tr>
<td>$M_{500} &gt; (M_{500})_{\text{mid}}$</td>
<td>2.45</td>
<td>0.68</td>
<td>0.07%</td>
<td>3.2</td>
</tr>
<tr>
<td>$R_{500} &lt; (R_{500})_{\text{mid}}$</td>
<td>0.48</td>
<td>0.68</td>
<td>23.7%</td>
<td>0.7</td>
</tr>
<tr>
<td>$R_{500} &gt; (R_{500})_{\text{mid}}$</td>
<td>2.80</td>
<td>0.68</td>
<td>0.02%</td>
<td>3.5</td>
</tr>
</tbody>
</table>

Notes. The number of sources in each split sample is 763.
4. Implications for the peculiar velocity field

We now want to investigate what the temperature dispersion indicates for the variance of the peculiar velocity field. As shown in Eq. (1), the dimensionless temperature fluctuation is different from the dimensionless velocity field through the line-of-sight optical depth factor $\tau$. Since the coherence length of the velocity field is order $100k^{-1}$ Mpc (Planck Collaboration Int. XXXVII 2016), i.e., much larger than the size of a cluster, the velocity can be taken out of the integral, giving

$$\frac{\Delta T(\hat{\mathbf{r}})}{T} = \left(\frac{-\hat{\mathbf{v}} \cdot \hat{\mathbf{r}}}{c}\right) \tau, \quad \text{with } \tau = \sigma_T \int_{r>0} n_{edl}. \quad (21)$$

In order to convert the kSZ signal into a line-of-sight velocity we therefore need to obtain an estimate of $\tau$ for each cluster. In Planck Collaboration Int. XIII (2014), the values calculated are explicitly given as the optical depth per solid angle, obtained based on two scaling relations from Arnaud et al. (2005 and 2010). Here we adopt a slightly different approach, which is to determine the $\tau$ value at the central pixel of each galaxy cluster.

Many of the previous studies of the tSZ effect have used the "universal pressure profile" (UPP, Arnaud et al. 2010; Planck Collaboration Int. V 2013) and isothermal $\beta$ model (Cavaliere & Fusco-Femiano 1976, 1978) to model the pressure and electron density profiles of the clusters (Grego et al. 2000; Benson et al. 2003, 2004; Hallman et al. 2007; Halverson et al. 2009; Plagge et al. 2010). Because the UPP is just a fitting function for pressure, it is difficult to separate out the electron density and the temperature unless we use the isothermal assumption. In fact, Battaglia et al. (2012) demonstrated that the UPP is not absolutely universal, and that feedback from an active galactic nucleus can change the profile in a significant way. The functional form of the $\beta$ model can be derived from a parameterization of density under the assumption of isothermality of the profile (e.g., Sarazin 1986). However, since isothermality is a poor assumption for many clusters (Planck Collaboration Int. V 2013), we only consider the $\beta$ model here as a fitting function. Measurements of cluster profiles from the South Pole Telescope (SPT) have found that the index $\beta = 0.86$ provides the best fit to the profiles of SZ clusters (Plagge et al. 2010), and therefore we use this value of $\beta$ in the following discussion.

The electron density can be written as

$$n_e(r) = \frac{n_{e0}}{1 + (r/r_c)^2}^{1/2}, \quad (22)$$

where $r_c = r_{vir}/c$ is the core radius of each cluster, with $c$ being the concentration parameter. Here we adopt the formula from Duffy et al. (2008) and Komatsu et al. (2011) to calculate the concentration parameter given the redshift and halo mass of the cluster:

$$c = \frac{5.72}{(1 + z)^{0.37}} \left(\frac{M_{vir}}{10^{14}h^{-1} M_\odot}\right)^{-0.081}. \quad (23)$$

In the catalogue, $M_{500}$ and redshift $z$ are given, so one can use these two quantities to calculate the virial mass $M_{vir}$ of the cluster. The calculation is contained in Appendix B.

The radius $r_{vir}$ is calculated through

$$M_{vir} = \frac{4\pi}{3} \left[\Delta(z)\rho_c(z)\right] r_{vir}^3, \quad (24)$$

where $\Delta(z)$ is the mass density contrast at redshift $z$, and $\rho_c(z)$ is the critical density at redshift $z$. The mass density contrast is defined as

$$\Delta(z) = \frac{\rho(z) - \rho_c(z)}{\rho_c(z)}.$$

The critical density at redshift $z$ is given by

$$\rho_c(z) = \frac{H(z)^2}{H^2} \rho_{crit},$$

where $H(z)$ is the Hubble parameter at redshift $z$. The Hubble parameter is given by

$$H(z) = h \sqrt{\Omega_m(1+z)^3 + \Omega_\Lambda + (1-\Omega_m-\Omega_\Lambda)(1+z)^2},$$

where $h$ is the Hubble constant in units of $100$ km/s/Mpc, $\Omega_m$ is the matter density parameter, and $\Omega_\Lambda$ is the dark energy density parameter. The equations for the Hubble parameter and mass density contrast are given in Appendix A.
where $n_\lambda(z)$ is the critical density of the Universe at redshift $z$, and $\Delta(z)$ depends on $\Omega_m$ and $\Omega_\Lambda$ as Bryan & Norman (1998)

$$\Delta(z) = 18\pi^2 + 82(\Omega(z) - 1) - 39(\Omega(z) - 1)^2,$$
with $\Omega(z) = \Omega_m(1 + z)^3 / \{\Omega_m(1 + z)^3 + \Omega_\Lambda\}$. Thus, 

$$\tau = (\sigma_T n_\lambda r_c) f_1(\beta),$$

where $f_1(\beta) = \int_{-\infty}^{+\infty} \frac{\Gamma(-0.5 + \frac{3}{2} \beta) - \Gamma(\frac{3}{2} \beta)}{\Gamma(\frac{3}{2} \beta)}\frac{dx}{(1 + x^2)^{3/2}},$ (26)

$$n_\lambda = \frac{1}{4\pi r_c^2 f_2(c_{500}, \beta)},$$

Here the quantity $f_1 = 0.76$ is the hydrogen mass fraction, $m_p$ is the proton mass, and $f_{gas} = (\Omega_b/\Omega_m)$ is the cosmic baryon fraction, while $M_{500}$ is the cluster mass enclosed in the radius $r_{500}$. Thus, 

$$\tau = \frac{(\sigma_T)^2 n_\lambda}{4\pi r_c^2 f_2(c_{500}, \beta)} \frac{x^2 dx}{(1 + x^2)^{3/2}},$$

(28)

Combining Eqs. (26), (27), and (28), we have 

$$\tau = \left(\frac{\sigma_T^2}{4\pi r_c^2}\right) \left(\frac{f_1}{f_2(c_{500}, \beta)}\right) \frac{f_{gas} M_{500}}{2m_p}.$$ 

In Fig. 13, we plot the histogram of the optical depth values of the 1526 clusters in the sample. The mean and standard deviation are given by $\tau = (3.9 \pm 1.2) \times 10^{-3}$. This is very consistent with the quoted value $\tau = (3.75 \pm 0.89) \times 10^{-3}$ from the cross-correlation between the kSZ SPT data and the photometric data from DES survey by fitting to a template of pairwise kSZ field (Soergel et al. 2016). Note that the uncertainty quoted here describes the scatter in the mean $\tau$ values for the whole of the sample.

We convert the temperature dispersion data listed in Table 5 to the line-of-sight velocity dispersion measurement by using the modelled value of $\tau$, after correcting by our estimate of the lensing effect. Our procedure is as follows. For each estimate of $\tau^2$, we correct by the estimated shift caused by lensing, then calculate its $v^2$ value, and obtain an averaged value of $v^2$ via

$$v^2 = \frac{c^2}{N_c} \sum_{i=1}^{N_c} \frac{r_i^2 f_{gas} M_{500}}{2m_p},$$

(30)

We then do this for the 5000 values of $\tau^2$, and plot the distribution (after shifting by the lensing effect) in the right panel of Fig. 10 for the 2D–ILC map. We also present results for $v^2$ in Table 8, where we can see that for the conservative case, i.e., the 2D–ILC map, the velocity dispersion is measured to be $v^2 = (12.3 \pm 7.1) \times (100 \text{ km s}^{-1})^2$. From the right panel of Fig. 10, we can see that the distribution is not completely Gaussian, but has a tail towards smaller $v^2$. The frequency $P(v^2 < 0)$ is 5.3%, which would correspond to a detection of the velocity dispersion from 1526 MCGX clusters at the 1.7 σ level (using Appendix C).

We also present results for $2D$–ILC and NILC, and plot the distribution of peculiar velocity fields, the most relevant quantity is the linear line-of-sight velocity ($v$), or in other words $\langle v^2 \rangle^{1/2}$. We find $\langle v^2 \rangle^{1/2} = (350 \pm 100) \text{ km s}^{-1}$ for the 2D–ILC map. One can see that the value we find is consistent with the velocity dispersion estimated through studies of the peculiar velocity field (e.g., Riess 2000; Turnbull et al. 2012; Ma & Scott 2013; Carrick et al. 2015).

Here we need to remember that what was measured is the line-of-sight velocity dispersion, which contains both the large-scale bulk flow, and the small-scale velocity and intrinsic dispersion (see, e.g., Ma & Scott 2014). The prediction for the rms bulk flow, Eq. (22) of Planck Collaboration Int. XIII (2014, or Eq. (4) in Ma & Pan 2014), is based on linear perturbation theory for the $\Lambda$CDM model and works only for the large-scale bulk flows. The small-scale motions and intrinsic dispersion are not fully predictable from linear perturbation theory because they depend on sub-Jeans scale structure evolution, which involves nonlinear effects. However, this small-scale velocity and intrinsic dispersion are nevertheless physical effects, which are non-negligible in general (Carrick et al. 2015). One should consider that the line-of-sight velocity dispersion that we have measured is a combination of two effects, namely large-scale bulk flows and small-scale intrinsic dispersion, where the second component is generally non-negligible.

We estimate that the histogram of separation distances between all pairs of cluster is peaked at $d \approx 600$ Mpc. Since the bulk flow contributes to the velocity dispersion measurement here, then we can set an upper limit on the cosmic bulk flow on scales of $600 h^{-1} \text{ Mpc}$, $(v_{500}^{bulk})^{1/2} < 554 \text{ km s}^{-1}$ (95% CL).
Such a constraint on large-scale bulk flows indicates that the Universe is statistically homogeneous on scales of 600 h⁻¹ Mpc. This is consistent with the limits obtained from Type-Ia supernovae (Feindt et al., 2013), the Spiral Field I-band survey (Nusser & Davis 2011; Ma & Scott 2013), ROSAT galaxy clusters (Mody & Hajian 2012), and the Planck peculiar velocity study (Planck Collaboration Int. XIII 2014). However, it does not allow the very large “dark flow” claimed in Kashlinsky et al. (2008, 2010, 2012) and Atrio-Barandela et al. (2015). In addition to ruling out such models, improved measurements of the velocity dispersion in the future have the potential to set up interesting constraints on dark energy and modified gravity (Bhattacharya & Kosowsky 2007, 2008).

5. Conclusions

The kinetic Sunyaev-Zeldovich effect gives anisotropic perturbations of the CMB sky, particularly in the direction of clusters of galaxies. Previous studies have detected the kSZ effect through the pairwise momentum estimator and temperature-velocity cross-correlation. In this paper, we have detected the kSZ effect through a measurement of the temperature dispersion and then we have interpreted this as a determination of the small-scale velocity dispersion of cosmological structure.

To do this, we first selected two sets of Planck foreground-cleaned maps. One set contains four Planck publicly available maps, namely SMICA, NILC, SEVEM, and Commander, each being produced using a different algorithm to minimize foreground emission. The second set is the Planck 2D-ILC map, which nulls the tSZ component, while resulting in slightly larger residual noise in the map. We then apply a matched-filter technique to the maps, to suppress the primary CMB and instrumental noise. We specifically consider the MCXC cluster sample. Applying a Galactic and point-source mask to the maps, results in 1526 MCXC clusters remaining unmasked.

We measured the distribution of the ΔT/T values for the 1526 MCXC cluster positions, and also at 1526 randomly selected positions, to give a quantification of the noise level. We found that the 1526 true cluster positions give extra variance to the distribution, and identify this as being due to the kSZ temperature dispersion effect. We compare this signal to results from 5000 random catalogues on the sky, each composed of 1526 random positions. This extra dispersion signal is persistent in several tests that we carry out.

We then construct estimators $\tilde{\Delta}$ to quantify this effect. For the SMICA, NILC, and SEVEM maps, the significance of detection is stronger than in the 2D-ILC map, which is likely due to the fact that the residual tSZ effect in the map is correlated with the kSZ signal. In addition, an analytical estimate, supported by simulations, shows that about 0.7 σ of the temperature-dispersion effect comes from gravitational lensing. By subtracting this effect through the pairwise momentum estimator and temperature corrections, shows that about 0.7 σ of the temperature-dispersion effect comes from gravitational lensing. By subtracting this effect, we obtain $\langle \frac{\Delta T}{T} \rangle = (1.35 \pm 0.48) \times 10^{-11} (68\%\text{ CL})$, where $\langle \frac{\Delta T}{T} \rangle = \frac{1}{N_{\text{clus}}} \sum_{j} (\Delta T_{j}/T_j)^2 (N_{\text{clus}} = 1526)$. This gives a detection of temperature dispersion at about the 2 σ level. We obtain largely consistent results when we obtain results by weighting clusters with their distance.

There are 1526 MCXC cluster positions, and also 1526 randomly selected positions, to give a quantification of the noise level. We obtain largely consistent results when we obtain results by weighting clusters with their distance.

References

Appendix A: The statistics of $s^2$

Let us first define the $k$th moment of a distribution of a random variable $x$ to be

$$\mu_k(x) \equiv E[x^k] = \frac{1}{N} \sum_i x_i^k.$$

(\ref{mom})

The $s^2$ estimator is defined in Eq. (16). Note that the observed $\delta^2_i$ is always taken to be the value of kSZ on the true cluster position, so there is no randomness in $\delta^2_i$. We also define

$$\overline{\delta^2} \equiv \frac{1}{N_c} \sum_i \delta_i^2.$$

(\ref{mean})

Therefore, the mean value of $\overline{s^2}$ is

$$E[\overline{s^2}] = \overline{\delta^2} - \bar{\mu}_2(n),$$

(\ref{mean2})

while the variance of $\overline{s^2}$ is

$$V[\overline{s^2}] = E[\overline{s^2}] - (E[\overline{s^2}])^2.$$

(\ref{var})

Therefore, we first calculate

$$s^2 = \left[ \overline{\delta^2} - \left( \frac{1}{N_c} \sum_i n_i^2 \right) \right]^2$$

$$= (\overline{\delta^2})^2 + \frac{1}{N_c} \sum_{ij} n_i^2 n_j^2 - \frac{2}{N_c} \overline{\delta^2} \left( \sum_i n_i^2 \right)$$

$$= (\overline{\delta^2})^2 + \frac{1}{N_c} \sum_i n_i^2 + \frac{1}{N_c} \sum_{i,j \neq i} n_i^2 n_j^2$$

$$- \frac{2}{N_c} \overline{\delta^2} \left( \sum_i n_i^2 \right).$$

(\ref{var2})

And hence,

$$E[s^2] = (\overline{\delta^2})^2 + \frac{1}{N_c} \mu_4(n) + \frac{N_c - 1}{N_c} (\mu_2(n))^2$$

$$- 2 \overline{\delta^2} \mu_2(n),$$

(\ref{var3})

where in the above derivation we have assumed that the residual noise samples in two different pixels are uncorrelated, i.e., $(n_i n_j) = 0$. Finally,

$$V[s^2] = \frac{1}{N_c} \left( \mu_2(n) - \mu_2^2(n) \right).$$

(\ref{var4})

Appendix B: Converting $M_{500}$ to $M_{\text{vir}}$

For each cluster, $M_{500}$ is defined as the mass within the radius of $R_{500}$, in which its average density is 500 times the critical density of the Universe,

$$M_{500} = \frac{4\pi}{3} [500\rho_c(z)] r_{500}^3,$$

(\ref{m500})

where

$$\rho_c(z) = 2.77h^2 E^2(z) \times 10^{11} M_{\odot} \text{Mpc}^{-3},$$

(\ref{rho})

and $E^2(z) = \Omega_m (1 + z)^3 + \Omega_{\Lambda}$. The quantity $M_{\text{vir}}$ is calculated via Eqs. (24) and (25), and the relationship between $M_{500}$ and $M_{\text{vir}}$ is Mody & Hajian (2012)

$$\frac{M_{500}}{M_{\text{vir}}} = \frac{m(\sigma_{500}/\sigma_{\text{vir}})}{m(c)},$$

(\ref{m500a})

where $c$ is the concentration parameter (Eq. (23)) and $m(x) = \ln(1 + x) - x/(1 + x)$. Given redshift $z$ and mass $M_{500}$, we can thus determine $r_{500}$ through Eq. (B.1). If we substitute $M_{500}$, $z$, and $r_{500}$ into Eq. (B.3), this becomes an algebraic equation for $M_{\text{vir}}$. This is because $r_{\text{vir}}$ can be determined from $M_{\text{vir}}$ through Eqs. (24) and (25), and $c$ is related to $M_{\text{vir}}$ through Eq. (23).

Therefore, we can iteratively solve for $M_{\text{vir}}$, given the values of $M_{500}$ and $z$.

Appendix C: Converting $P$ values into S/Ns

Since the distribution of weighted $s^2$ has a longer tail than a Gaussian distribution, instead of calculating the ratio between mean and rms values of the distribution, we calculate the $p$-values, and list them in the third column of Table 6. We now convert them into S/N in the following way. Suppose the variable $x$ satisfies a Gaussian distribution, the normalized distribution is $L(x) = (1/\sqrt{2\pi}\sigma) \exp(-(x - \mu)^2/2\sigma^2)$. Then the cumulative probability to find $x < 0$ is

$$\epsilon = \int_{-\infty}^{0} P(x) dx = \frac{1}{2} \text{Erfc} \left( \frac{\mu}{\sqrt{2}\sigma} \right),$$

(\ref{erfc})

where

$$\text{Erfc}(x) = \frac{2}{\sqrt{\pi}} \int_{x}^{\infty} e^{-t^2} dt,$$

(\ref{erfc2})

is the complimentary error function.

Therefore the equivalent S/N given the value of $P(s^2_w < 0)$ is

$$S/N = \sqrt{2} \left[ \text{Erfc}^{-1} \left( 2P(s^2_w < 0) \right) \right].$$

(\ref{sn})

We use Eq. (C.3) to obtain the fourth column of Table 6.