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Modeling growth kinetics of thin films made by atomic layer deposition in lateral high-aspect-ratio structures

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The conformality of thin films grown by atomic layer deposition (ALD) is studied using all-silicon test structures with long narrow lateral channels. A diffusion model, developed in this work, is used for studying the propagation of ALD growth in narrow channels. The diffusion model takes into account the gas transportation at low pressures, the dynamic Langmuir adsorption model for the film growth and the effect of channel narrowing due to film growth. The film growth is calculated by solving the diffusion equation with surface reactions. An efficient analytic approximate solution of the diffusion equation is developed for fitting the model to the measured thickness profile. The fitting gives the equilibrium constant of adsorption and the sticking coefficient. This model and Gordon’s plug flow model are compared. The simulations predict the experimental measurement results quite well for Al2O3 and TiO2 ALD processes. Published by AIP Publishing. https://doi.org/10.1063/1.5028178

NOMENCLATURE

\[ a \] Aspect ratio
\[ b \] Number of metal atoms in a molecule
\[ c \] Lumped sticking coefficient
\[ C \] Penetration depth parameter in the Gordon model \((1/s)\)
\[ D \] Apparent longitudinal diffusion coefficient \((m^2/s)\)
\[ d_A \] Diameter of molecule A \((m)\)
\[ D_A \] Gas-phase diffusion coefficient of molecules A \((m^2/s)\)
\[ D_{\text{eff}} \] Effective diffusion coefficient \((m^2/s)\)
\[ D_{Kn} \] Knudsen diffusion coefficient \((m^2/s)\)
\[ F \] Gas flow of the reactant \((mol/s)\)
\[ f_{\text{ads}} \] Adsorption rate \((m^-2s^-1)\)
\[ f_{\text{des}} \] Desorption rate \((m^-2s^-1)\)
\[ g \] Net adsorption rate \((m^-2s^-1)\)
\[ g_{pc} \] Film growth per cycle \((m)\)
\[ g_{pc,\text{sat}} \] Saturation growth in cycle \((m)\)
\[ F \] Hydraulic diameter of the channel \((m)\)
\[ H \] Height of the channel \((m)\)
\[ K \] Adsorption equilibrium constant \((1/Pa)\)
\[ L \] Length of the channel \((m)\)
\[ M \] Molar mass of the deposited film \((kg/mol)\)
\[ M_A \] Molar mass of reactant A \((kg/mol)\)
\[ N \] Total number of adsorbed molecules; number of ALD cycles
\[ n_A \] Amount of reactant A \((mol)\)
\[ N_0 \] Avogadro constant \((1/mol)\)
\[ p_A \] Partial pressure of reactant A \((Pa)\)
\[ P_{A0} \] Input partial pressure of reactant A \((Pa)\)
\[ P_d \] Desorption probability in unit time \((1/s)\)
\[ q \] Adsorption density of molecules in saturation \((1/m^2)\)
\[ Q \] Collision rate at unit pressure \((m^-2s^-1Pa^-1)\)
\[ R \] Gas constant \((J K^-1 mol^-1)\)

\[ s \] Film thickness \((m)\)
\[ t \] Time \((s)\)
\[ T \] Temperature \((K)\)
\[ t_P \] Length of the reactant pulse \((s)\)
\[ v \] Velocity of gas front \((m/s)\)
\[ v_A \] Average speed of molecules A \((m/s)\)
\[ W \] Width of the channel \((m)\)
\[ x \] Distance from the beginning of the channel \((m)\)
\[ x_p \] Half-thickness penetration depth \((m)\)
\[ x_s \] Distance where the linear part of the reactant pressure is zero \((m)\)
\[ x_i \] Length of the linear part of the pressure distribution \((m)\)
\[ z_A \] Collision rate of molecule A \((1/s)\)
\[ \Delta s \] Error in thickness measurement \((m)\)
\[ \eta \] Viscosity of gas \((Pa s)\)
\[ \theta \] Surface coverage
\[ \theta_{\text{eq}} \] Equilibrium surface coverage in the Langmuir model
\[ \rho \] Density of the condensed phase \((kg/m^3)\)
\[ \tau \] Time constant of adsorption

I. INTRODUCTION

The downscaling of future semiconductor devices with increasing three-dimensionality—e.g., through-silicon-vias, FinFETS, 3D-NAND flash memories—sets new requirements for the aspect ratios which thin film processes have to conformably reach. Atomic layer deposition (ALD), based on the use of repeated, self-terminating reactions of typically at least two compatible reactants on a solid substrate (Puurunen, 2005 and George, 2010), is a technique that can often meet the conformity requirements. Conformal films made by ALD are also needed in other fields, with intrinsic three-dimensionality requirements, such as microelectromechanical systems (MEMS), energy applications, and high-surface-area catalysts. Despite its importance, experimental
data on conformality has been infrequently reported in scientific articles on ALD, likely due to the absence of available and easy-to-use analysis structures and methods. Notable exceptions are Dendooven (2010), Rose and Bartha (2009), Schwille (2017), and Yanguas-Gil (2017).

This work continues the earlier work (Gao, 2015), where microscopic lateral high-aspect-ratio structure (LHAR) prototypes were designed and fabricated. The LHAR structures consist of a long, narrow lateral gap of typically 500 nm in height (analogous to a vertical trench but rotated 90°) in a polysilicon membrane, supported by pillars. The first LHAR prototypes have been used for conformality analysis of the ALD Al2O3-, TiO2- and Ir-based thin films (Gao, 2015; Mattinen, 2016; and Puurunen and Gao, 2016). This work uses LHAR (PillarHall®) prototypes with a new all-silicon design made by a fabrication process resembling that previously reported (Gao, 2015). The length of the fabricated channels varied from 1 μm to 5 mm, so that for a typical gap height of 500 nm, the gap length vs. height gives the aspect ratio in the range from 2:1 to 10 000:1. It turned out that the penetration depth does not depend on the length of the channel when it is long enough. The structure of the LHAR test device is schematically illustrated in Fig. 1.

The goal of this work is to develop a model to calculate the thickness profile of ALD growth in high-aspect-ratio trenches. Using this model, the measured ALD film thickness profiles can be used to extract kinetic growth information. The derived model and its analytical simplification are compared with the Gordon model (Gordon, 2003). The frequently used trimethylaluminum-water (TMA) process for Al2O3 and the chloride process for TiO2 have been used to verify the model.

II. GAS DIFFUSION IN NARROW CHANNELS

The hard-sphere model of molecules (Levine, 1978) can satisfactorily explain the diffusion properties of bulk gas mixtures. If the partial pressures of molecules A and B are $p_A$ and $p_B$, their molar masses $M_A$ and $M_B$ and diameters $d_A$ and $d_B$, respectively, the collision rate of A molecules in a gas mixture A + B at temperature $T$ is given by

\[ z_A = \frac{\pi}{4} (d_A + d_B)^2 \left[ \frac{8RT}{\pi} \left( \frac{1}{M_A} + \frac{1}{M_B} \right) \right]^{1/2} \frac{p_B}{RT} \]

\[ + \frac{\pi (d_A)^2}{\pi M_A} \left[ \frac{16RT}{\pi M_A} \right]^{1/2} \frac{p_A}{RT}, \]  

where the latter term is the rate of A-A collisions. $R = k_B N_0$ is the gas constant where $k_B$ is the Boltzmann constant and $N_0$ the Avogadro constant. The average speed of A molecules is

\[ v_A = \left( \frac{8RT}{\pi M_A} \right)^{1/2}. \]

The gas-phase diffusion constant of A molecules is

\[ D_A = \frac{3\pi v_A^2}{16 z_A}. \]

The diffusion model of mass transport in narrow channels can be extended to the transition flow regime if the effect of walls is incorporated into the model. The diffusion constant in a molecular (Knudsen) flow is (Poodt, 2017)

\[ D_{Kn} = h \left( \frac{8RT}{9\pi M_A} \right)^{1/2}, \]

where

\[ h = \frac{2}{H + \frac{1}{W}} \]

is the hydraulic diameter of a rectangular channel of height $H$ and width $W$.

The diffusion resistance is the sum of bulk diffusion in gas and wall collisions. The combined diffusion constant in a narrow channel at low pressures follows the Bosanquet relation (Poodt, 2017)

\[ D_{eff} = \frac{1}{D_A + D_{Kn}}. \]

Calculation of the diffusion constant $D_A$ requires a value for the diameter $d_A$ of the molecule. For common gases, this can be calculated, e.g., from the gas phase viscosity $\eta$ (Levine, 1978)

\[ d_A \approx \sqrt{\frac{5}{16\eta N_0}} \sqrt{\frac{M_A RT}{\pi}}. \]

The viscosity of water vapor at 100 °C is $\eta = 12.55$ μPa s (Weast, 1977), which gives a molecular diameter $d_A = 418$ pm. For nitrogen at 11 °C, $\eta = 17.07$ μPa s and $d_B = 374$ pm. For most reactants in ALD, the gas phase viscosity is not measured. The molecular diameter can be calculated from a molecular dynamics simulation, but because the Knudsen diffusion is the major limiting factor in the mass transport in narrow channels, a rough estimate of the molecular diameter is sufficient. We obtain it from the density $\rho$ of the liquid or solid phase of the material.
Trimethylaluminum (TMA, Al(CH₃)₃) exists at low temperatures in a dimeric form, but above 215 °C, more than 96% is in the monomeric form (Almenningen, 1971). Therefore, the diffusion constant of the monomer is used. The molecular diameters of metal precursors used here are d_{TMA} = 591 pm and d_{TiCl₄} = 703.9 pm.

For the modeling of the mass transport in ALD, we need to quantify the amount of material that chemisorbs on the surface in one reaction cycle. This depends on the adsorption density \( q \) of the reactant molecules. If the experimental saturation growth per cycle is \( g_{pc_{sat}} \) (layer thickness per cycle at saturation reactant exposure) is available, we can calculate the adsorption density \( q \) from the film mass density \( \rho \)

\[
q = \frac{2 \, b_{fim} \, \rho \, g_{pc_{sat}}}{M} N_0. \tag{9}
\]

Here, \( b_{fim} \) is the number of metal atoms in the formula unit of the deposited film and \( b_A \) the number of metal atoms in one reactant molecule. \( M \) is the molar mass of a formula unit of the film. For TMA and Al₂O₃, these are \( b_{fim} = 2 \) and \( b_A = 1 \), and for TiCl₄ and TiO₂, \( b_{fim} = 1 \) and \( b_A = 1 \).

Because the weight and the size of water molecules are smaller than those of the metal reactants they diffuse much more rapidly than the metal compounds and the growth-limiting factor is assumed to be the diffusion of metal precursors.

**III. MODELING THE FILM GROWTH**

The coordinate system used in the high-aspect-ratio lateral channel is defined in Fig. 1. The gas enters from the left and propagates along the x-axis by diffusion. In the y-direction (height), the time constant for concentration equilibration by diffusion is \( H^2 / D_{eff} \approx 10 \) ns, where the channel height \( H = 1 \) \( \mu \)m and the effective diffusion coefficient \( D_{eff} \) is typically about 1 \( \text{cm}^2/\text{s} \). Therefore, we may assume well that there are no concentration gradients in the y-direction in the millisecond time scale of the ALD process. In the z-direction, the channel is very wide (\( W \gg H \)), and therefore the concentration is assumed constant in that direction.

We can now simplify the problem by using the fact that the gas concentration is constant in the \( y \) and \( z \) directions. The one-dimensional diffusion equation for partial pressure \( p_A \) is

\[
\frac{\partial p_A}{\partial t} = D_{eff} \frac{\partial^2 p_A}{\partial x^2} - \frac{4 \, RT \, g}{h \, N_0}, \tag{10}
\]

where the gas adsorption rate to the walls is \( g \) (\( 1/\text{m}^2 \text{s} \)). This equation can be solved numerically, but when the number of reactant pulses in an ALD process can be several thousands the computational task is impractically heavy.

Although the surface reactions may be very complicated, we use the Langmuir adsorption model for the chemisorption process. With sticking probability \( c \) the rate of adsorption (\( 1/\text{m}^2 \text{s} \)) (Levine, 1978) is

\[
f_{ads} = (1 - \theta) \frac{c N_0 p_A}{\sqrt{2 \pi M_A RT}}. \tag{11}
\]

and the rate of desorption is

\[
f_{des} = q \theta P_d, \tag{12}
\]

where \( \theta \) is the surface coverage, \( q \) the saturation adsorption density, and \( P_d \) the desorption probability in unit time. Here, \( c \) must be understood as a lumped sticking coefficient which combines the effects of all sequential and parallel surface processes.

In equilibrium, these are equal and we can define the adsorption equilibrium constant \( K \) using the collision rate at unit pressure \( Q \) (Levine, 1978)

\[
K = \frac{\theta_{eq} / p_A}{1 - \theta_{eq} / q P_d}, \tag{13}
\]

\[
Q = \frac{N_0}{\sqrt{2 \pi M_A RT}}. \tag{14}
\]

The net adsorption rate \( g \) (\( 1/\text{m}^2 \text{s} \)) of gas \( A \) is

\[
g = f_{ads} - f_{des}, \tag{15}
\]

and the rate of change in the surface coverage \( \theta \) is

\[
\frac{d \theta}{d t} = -\frac{g}{q}. \tag{16}
\]

During the reactant pulse, the net adsorption rate is always positive so that the question whether the adsorption is reversible or irreversible is not important for this model. Both cases are covered by the Langmuir model; in the latter case, \( P_d = 0 \). Experiments show that better fit, especially in the case of TiO₂ is obtained if \( P_d > 0 \). Although the Langmuir model is used in this analysis, the actual reaction mechanism may be much more complicated.

**IV. APPROXIMATE SOLUTION TO THE DIFFUSION EQUATION**

We need a simple approximate model for the reactant gas partial pressure \( p_A \) as a function of location \( x \) and time \( t \), so that we do not need to find a numerical solution of the diffusion equation in fitting the model to the measured results. In the beginning of the channel, the surfaces are immediately saturated and no gas is used in adsorption \( g(x = 0) \approx 0 \). The gas flow is in the steady state (\( \partial p_A / \partial t \approx 0 \)) and the diffusion equation is simplified to

\[
D_{eff} \frac{\partial^2 p_A(x, t)}{\partial x^2} \approx 0. \tag{17}
\]

Its solution is

\[
p_A(x, t) = p_{A0} \left( 1 - \frac{x}{x_t} \right), \quad x < x_t, \tag{18}
\]

where the boundary conditions \( p_A(0, t) = p_{A0} \) and \( p_A(x_t, t) \approx 0 \) have been used. \( x_t \) is the limit beyond which the approximation \( g \approx 0 \) is not valid and \( x_t \) describes how far the reactant front has propagated at time \( t \). It is the location where the linear part of the pressure distribution would go to zero.
Because the gas propagates by diffusion, a reasonable approximation is that the growth distance is proportional to the diffusion length (Yanguas-Gil, 2017)

\[ x_s = \sqrt{Dt}. \]  

(19)

Here, \( D \) is a parameter (apparent longitudinal diffusion constant) describing the velocity of the gas front. In the region on linear pressure distribution (\( x < x_t \)) and when the surfaces are saturated, the diffusion gas flow (molecules/s)

\[ F(x, t) = -\frac{D_{\text{eff}}}{k_B T} \frac{\partial p_A}{\partial x} \approx \frac{p_{\text{eq}}}{k_B T} D_{\text{eff}} \frac{1}{x_s}. \]  

(20)

The total number of molecules adsorbed onto the surfaces at distance \( x \) is

\[ N = \int_0^x 2qWdx = 2qW \left( \frac{x}{Kp_{\text{eq}}} \ln \left( \frac{1 - \frac{x}{x_s}}{Kp_{\text{eq}}} + 1 \right) \right). \]  

(21)

When we neglect the small amount \( n_s \approx \frac{p_{\text{eq}}}{k_B T} Wx_p(2RT) \) of yet unused reactant in the gas phase, this must be equal to the integrated gas flow at time \( t \)

\[ \int_0^t F(x, t) dt = N, \]

\[ \int_0^{p_{\text{eq}}} \frac{2D_{\text{eff}}}{k_B T} \frac{dt}{\sqrt{Dt}} = \int_0^x \frac{dp_A}{k_B T} \frac{dx}{\sqrt{Dt}} = 2qWx_s + 2qW \frac{x_s}{Kp_{\text{eq}}} \ln \left( \frac{1}{Kp_{\text{eq}}} + 1 \right). \]  

(22)

From this, we can solve the apparent longitudinal diffusion constant which is needed to calculate \( x_t \) in (19)

\[ D = \frac{p_{\text{eq}}HD_{\text{eff}}}{qk_B T \left( 1 - \frac{1}{\ln(Kp_{\text{eq}} + 1)} \right)}. \]  

(23)

In the constant-slope region \( x < x_t \), the pressure is approximated by the linear model (18). Beyond point \( x_t \) (in the tail region), we approximate the partial pressure by an exponential tail and we use the following model to describe the reactant pressure

\[ p_A(x, t) = p_{\text{eq}} \left( 1 - \frac{x}{x_s} \right), \quad x < x_t, \]

\[ p_A(x, t) = p_t \exp \left( -\frac{x - x_t}{x_s - x_t} \right), \quad x > x_t, \]

\[ p_t = \frac{p_{\text{eq}}}{1 + \frac{x_t}{x_s}}, \]

\[ x_s = \sqrt{Dt}. \]  

(24)

The point \( x_t \) is chosen, so that the pressure is continuous. In the tail region \( (x > x_t) \),

\[ \frac{dp_A}{dt} = \frac{D_p}{p_t} \exp \left( \frac{x - x_t}{x_s - x_t} \right) \frac{(x - x_t)}{2x_s(x_s - x_t)^2}, \]

\[ \frac{d^2p_A}{dt^2} = \frac{p_t}{p_t} \frac{x - x_t}{(x_s - x_t)^2}. \]  

(25)

When these are inserted in the diffusion equation, Eq. (10), we get

\[ D_p \exp \left( \frac{x - x_t}{x_s - x_t} \right) \frac{(x - x_t)}{2x_s(x_s - x_t)^2} \]

\[ = D_{\text{eff}} \frac{x - x_t}{x_s - x_t} - \frac{4RT}{h N_0} (1 - 0) cQ p_t \]

\[ \times \exp \frac{x - x_t}{x_s - x_t} + \frac{4RT}{h N_0} q d\theta d. \]  

(26)

In the tail region, the surface coverage is low. When \( \theta \approx 0 \), we have

\[ D = \frac{(x - x_t)}{2x_s(x_s - x_t)^2} \approx \frac{D_{\text{eff}}}{(x_s - x_t)^2} - \frac{4RT}{h N_0} cQ. \]  

(27)

Now, we choose \( x_t \), so that this equation is true at location \( x = x_s \), but \( x_t \) must not be negative

\[ x_t = x_s - \sqrt{\frac{h N_0 D_{\text{eff}}}{4RT cQ}}, \quad \text{if} \quad x_s > \sqrt{\frac{h N_0 D_{\text{eff}}}{4RT cQ}}; \]

\[ x_t = 0, \quad \text{otherwise}. \]  

(28)

In Fig. 2, this approximate model is compared with the numerical solution of the diffusion equation and the fit looks quite good.

Next, we need a solution for the surface coverage \( \theta \) at point \( x \) at time \( t \). If the gas pressure changes slowly compared to the rate of adsorption, we may assume that the adsorption is in equilibrium and the surface coverage at location \( x \) would be

\[ \theta_{\text{eq}}(x) = \frac{Kp_A(x)}{1 + Kp_A(x)}. \]  

(29)

At constant \( p_A \), the surface coverage \( \theta \) approaches exponentially the equilibrium coverage and the time constant of this process when \( \theta_{\text{eq}} = 0.5 \) is

\[ \tau = \frac{QK}{2cQ}. \]  

(30)

The equilibrium model is sufficiently accurate if \( \tau \) is much smaller than the pulse length \( t_p \). However, in real ALD processes, the adsorption can be far from equilibrium, and thus this assumption is not useful.

The surface coverage \( \theta(x, t) \) in the Langmuir model can always be found by solving

\[ \frac{d\theta(x, t)}{dt} = \frac{cQp_A(x, t)}{q} - \left( \frac{cQp_{\text{eq}}(x, t)}{q} + P_d \right) \theta(x, t). \]  

(31)
The analytical solution is (integrations from 0 to t)

$$\theta(t) = e^{-\int \left(\frac{\phi p_A + p_e}{q} \right) dt} \int \frac{cQ}{q} p_A e^{-\int \left(\frac{\phi p_A + p_e}{q} \right) dt} dt. \tag{32}$$

Because typically we need to solve Eq. (31) more than 10,000 times in fitting the result of one growth experiment, it is the major time consuming step in the analysis. Numerical integration of Eq. (32) is too slow. In this work, Eq. (31) is solved by the 4th order Runge-Kutta method (Arfken, 1970). It is self-initiated and easily stable. Often, 100 time points (time step, e.g., 1 ms) are enough for accurate results. However, sometimes this does not guarantee convergence and then we need to increase the number of time points.

In Figs. 2 and 3, this approximate model is compared with the numerical solution of the differential equations. Both models give practically identical results.

V. THICKNESS PROFILE AND THE PENETRATION DEPTH

In an ALD growth experiment, N cycles of reactant pulses consisting of the first reactant (e.g., TMA) and the second reactant (H$_2$O) are fed into the channel, and the resulting thickness profile $s(x)$ is measured. When the penetration depth $x_p$ is determined by measuring the film thickness $s$, the error in it is

$$\Delta x_p = \frac{\Delta s}{ds/dx} \tag{33}$$

where $\Delta s$ is the error in film thickness and $ds/dx$ is the slope of the film thickness vs. location at the point of measurement. The maximum value of the slope is at the point of half film thickness and determining $x_p$ at this point gives the best accuracy. Therefore, we define the half-thickness penetration $x_p$ of the film growth, so that the film thickness is 50% of thickness $s(0)$ at the beginning of the channel, or by solving $x_p$ in the equation

$$s(x_p) = \frac{s(0)}{2}. \tag{34}$$

The film grows on both the top and bottom surfaces of the channel. If the thickness growth of the film in one complete growth cycle is $gpc$, the free height of the channel after $N$ cycles is

$$H(N) = H(0) - 2Ngpc. \tag{35}$$

Because the film growth thickness depends on location $x$, the channel height also varies with location. This complicates the analysis because the diffusion constant now depends on location. This problem is circumvented by assuming that the channel height is constant in the whole channel and it is updated to the value in the beginning of the channel after each pulse. Thus, in the model, the channel in the tail region is narrower than in reality, so the model predicts slightly too steep thinning of the film. However, this is a good assumption when the film is thin compared to the gap height $H$ and when the film does not grow much beyond the point $x_p$.

In the last step, we add the contributions $\theta_i$ in the surface coverage of all the $N$ cycles and compute the final thickness distribution $s(x)$

$$\theta(x) = \sum_{i=1}^{N} \theta_i(x), \tag{36}$$

$$s(x) = \theta(x)gpc_{sat}. \tag{37}$$

The resulting film thickness distributions with different channel height values are shown in Fig. 4.
When the surface is saturated, there is no absorption and this flow \( F \) (1/s) of incoming gas in time \( dt \)

\[
dN = F dt.
\]

When the surface is saturated, there is no absorption and this location \( x \) propagates with velocity \( v \)

\[
v = \frac{dx}{dt} = \frac{F}{2qW}.
\]

The flow through a channel of length \( x \) and area \( WH \) in a molecular flow is approximated by Gordon (2003)

\[
F = \frac{p_{A0}N_0}{\sqrt{2\pi M_A RT}} \cdot \frac{WH}{1 + \frac{3x}{8} \left( \frac{1}{H} + \frac{1}{W} \right)}.
\]

This can be separated and integrated as

\[
x + \frac{3x^2}{16} \left( \frac{1}{H} + \frac{1}{W} \right) = \frac{HP_{A0}N_0}{2q\sqrt{2\pi M_A RT}t}.
\]

In the Gordon model, the aspect ratio \( \alpha = x/H \) is independent of height \( H \) of the channel. If we denote

\[
C = \frac{p_{A0}N_0}{2q\sqrt{2\pi M_A RT}},
\]

we get the penetration depth at pulse length \( t_p \), when \( W \gg H \)

\[
x_p = H \sqrt{1 + \frac{3}{4} C \rho_p - 1}.
\]

This is plotted in Fig. 5 for one ALD cycle and compared with the present diffusion models. Although the Gordon model in this case gives a good description of the film penetration depth, it does not give the thickness profile and it does not enable modeling of the film growth kinetics.

**VI. COMPARISON WITH THE GORDON MODEL**

In the Gordon model for ALD conformality, it is assumed that the gas enters the rectangular channel (height \( H \ll \) width \( W \)) as a front with a constant concentration without any gas diffusion in the propagation direction (x-axis). This is called the Gordon model (Gordon, 2003). Gas is adsorbed onto the two walls. When \( q \) is the saturation areal density (m\(^{-2}\)) of the adsorbed molecules, the number of adsorbed molecules at distance \( dx \) in a channel with width \( W \) is

\[
dN = 2qWdx.
\]

On the other hand, the number of molecules is equal to the flow \( F \) (1/s) of incoming gas in time \( dt \)

\[
dN = F dt.
\]

FIG. 4. Film thickness profiles after 1000 cycles calculated by the approximate model when the original channel heights are \( H = 2, 1, 0.5, \) or 0.2 \( \mu m \). Reactant pulse length \( t_p = 0.1 \) s. In the last case, the channel entrance is completely plugged up. Parameter values used: \( H = 0.5 \mu m, W = 0.1 \mu m, p_{A0} = 100 \text{Pa}, M_A = 0.0749 \text{kg/mol}, d_A = 591 \text{pm}, d_B = 374 \text{pm}, p_B = 300 \text{Pa}, q = 5 \times 10^{13} \text{m}^{-2}, T = 500 \text{K}, K = 100 \text{Pa}^{-1}, \epsilon = 0.01, \) and \( gpc_{sat} = 106 \text{pm} \).

**VII. EXPERIMENTAL**

To test the growth model, ALD Al\(_2\)O\(_3\) and TiO\(_2\) films were grown on LHAR structures. The ALD reactor was a Picosun R-150 with four reactant lines. Al\(_2\)O\(_3\) was grown from trimethylaluminum (TMA) and water (H\(_2\)O) at 300°C and TiO\(_2\) from titanium tetrachloride (TiCl\(_4\)) and H\(_2\)O at 110°C. Nitrogen was used as the carrier gas. The ALD process was modeled with a Monte Carlo simulation tool (Gao, 2015). The simulation tool was used to predict the film thickness profiles. The Monte Carlo simulation tool was compared with the experimental results. The simulation results were in good agreement with the experimental results. The simulation tool was used to predict the film thickness profiles for different process parameters. The simulation results were in good agreement with the experimental results. The simulation tool was used to predict the film thickness profiles for different process parameters.
used both as a purging gas and as a carrier gas for the reactants. The LHAR chips (PillarHall® 3rd generation prototypes by VTT) were thermalized in the ALD chamber at the deposition temperature for 10 min before starting the growth process. For Al₂O₃ growth, the AlMe₃ pulse and purge times were 0.1 and 4.0 s, respectively, followed by 0.1 and 4.0 s H₂O pulse and purge steps. This reaction sequence was repeated for 500 cycles, leading approximately to 50 nm film. Chamber pressures for both Al₂O₃ and TiO₂ during the runs were appr. 300 Pa.

The LHAR structures were inspected optically after the ALD before and after removing the membrane. The film growth depth was determined by spectroscopic reflectometry measurements using SCI FilmTek 2000M equipment, and the samples were measured using a 100-point line scan. The measurement started at the beginning of the lateral cavity proceeding in 2 μm steps towards the cavity end; thus, the total scan length was 200 μm. In the measurement, a 50× objective lens was used, giving roughly 5 μm spot size. The precision of the film thickness measurement is limited by the roughness of the channel surface and we estimate it to be about 3 nm.

**VIII. RESULTS**

The measured and calculated thickness profiles of Al₂O₃ and TiO₂ films are given in Figs. 6 and 7. The extracted growth parameters are in Table I. The saturation growth in one cycle \( gpc_{sat} \) is the equilibrium thickness of layer growth at saturation or high reactant exposure or

\[
gpc_{sat} = \frac{1 + KP_A}{KP_A} gpc,
\]

where \( gpc \) is the observed growth per cycle at reactant pressure \( P_A \) and \( K \) is the equilibrium constant in the Langmuir model. The thickness error is the rms difference between the measured and calculated thicknesses and describes how well the modeling describes the measured result.

The ALD thickness profiles of Al₂O₃ and TiO₂ films are quite different. Aluminum oxide film exhibits constant thickness from the beginning to close to the penetration depth. Titanium oxide thickness is nowhere constant but the film thickness gradually decreases when the gas enters deeper into the channel. In the Langmuir model, this results in quite different values for the sticking coefficient \( c \) and the equilibrium constant \( K \). The root cause probably is that the deposition of TiO₂ produces very reactive HCl (Knapas and Ritala, 2013), while the Al₂O₃ deposition produces relatively passive CH₄ (Puurunen, 2005). If we knew the reaction mechanism, it could be used to replace the Langmuir adsorption equation, Eq. (31), and the present fitting procedure could then be used to find out the model parameters.

**IX. CONCLUSIONS**

The model presented here describes quite well the thickness distribution of ALD growth in narrow channels. This
model can be used to design and optimize a deposition process for a new device. By fitting the model to the measured thickness distribution, one obtains parameters of the growth reaction model used. Here, only the simple Langmuir surface reaction model is applied, but it can be replaced by any model by changing Eq. (31). More elaborate models require more numerous parameters and their determination requires a more extensive set of measured data.

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